Pro-Flo® Controller GMT 360

Customer Product Manual
Part 303 865A

NORDSON CORPORATION • AMHERST, OHIO • USA

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Notice

Trademarks

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Section 1

Safety

Section 1
Safety

1. Introduction

Read and follow these safety instructions. Task- and equipment-specific warnings, cautions, and instructions are included in equipment documentation where appropriate.

Make sure all equipment documentation, including these instructions, is accessible to persons operating or servicing equipment.

2. Qualified Personnel

Equipment owners are responsible for making sure that Nordson equipment is installed, operated, and serviced by qualified personnel. Qualified personnel are those employees or contractors who are trained to safely perform their assigned tasks. They are familiar with all relevant safety rules and regulations and are physically capable of performing their assigned tasks.

3. Intended Use

Use of Nordson equipment in ways other than those described in the documentation supplied with the equipment may result in injury to persons or damage to property.

Some examples of unintended use of equipment include

- using incompatible materials
- making unauthorized modifications
- removing or bypassing safety guards or interlocks
- using incompatible or damaged parts
- using unapproved auxiliary equipment
- operating equipment in excess of maximum ratings

4. Regulations and Approvals

Make sure all equipment is rated and approved for the environment in which it is used. Any approvals obtained for Nordson equipment will be voided if instructions for installation, operation, and service are not followed.

5. Personal Safety

To prevent injury follow these instructions.

- Do not operate or service equipment unless you are qualified.
- Do not operate equipment unless safety guards, doors, or covers are intact and automatic interlocks are operating properly. Do not bypass or disarm any safety devices.
- Keep clear of moving equipment. Before adjusting or servicing moving equipment, shut off the power supply and wait until the equipment comes to a complete stop. Lock out power and secure the equipment to prevent unexpected movement.
- Relieve (bleed off) hydraulic and pneumatic pressure before adjusting or servicing pressurized systems or components. Disconnect, lock out, and tag switches before servicing electrical equipment.
- While operating manual spray guns, make sure you are grounded. Wear electrically conductive gloves or a grounding strap connected to the gun handle or other true earth ground. Do not wear or carry metallic objects such as jewelry or tools.
- If you receive even a slight electrical shock, shut down all electrical or electrostatic equipment immediately. Do not restart the equipment until the problem has been identified and corrected.
- Obtain and read Material Safety Data Sheets (MSDS) for all materials used. Follow the manufacturer's instructions for safe handling and use of materials, and use recommended personal protection devices.
- Make sure the spray area is adequately ventilated.
- To prevent injury, be aware of less-obvious dangers in the workplace that often cannot be completely eliminated, such as hot surfaces, sharp edges, energized electrical circuits, and moving parts that cannot be enclosed or otherwise guarded for practical reasons.

High-Pressure Fluids

High-pressure fluids, unless they are safely contained, are extremely hazardous. Always relieve fluid pressure before adjusting or servicing high pressure equipment. A jet of high-pressure fluid can cut like a knife and cause serious bodily injury, amputation, or death. Fluids penetrating the skin can also cause toxic poisoning.

If you suffer a fluid injection injury, seek medical care immediately. If possible, provide a copy of the MSDS for the injected fluid to the health care provider.

The National Spray Equipment Manufacturers Association has created a wallet card that you should carry when you are operating high-pressure spray equipment. These cards are supplied with your equipment. The following is the text of this card:

WARNING: Any injury caused by high pressure liquid can be serious. If you are injured or even suspect an injury:

- Go to an emergency room immediately.
- Tell the doctor that you suspect an injection injury.
- Show him this card.
- Tell him what kind of material you were spraying.

MEDICAL ALERT–AIRLESS SPRAY WOUNDS: NOTE TO PHYSICIAN

Injection in the skin is a serious traumatic injury. It is important to treat the injury surgically as soon as possible. Do not delay treatment to research toxicity. Toxicity is a concern with some exotic coatings injected directly into the bloodstream.

Consultation with a plastic surgeon or a reconstructive hand surgeon may be advisable.

The seriousness of the wound depends on where the injury is on the body, whether the substance hit something on its way in and deflected causing more damage, and many other variables including skin microflora residing in the paint or gun which are blasted into the wound. If the injected paint contains acrylic latex and titanium dioxide that damage the tissue's resistance to infection, bacterial growth will flourish. The treatment that doctors recommend for an injection injury to the hand includes immediate decompression of the closed vascular compartments of the hand to release the underlying tissue distended by the injected paint, judicious wound depravement, and immediate antibiotic treatment.

6. Fire Safety

To avoid a fire or explosion, follow these instructions.

- Ground all conductive equipment in the spray area. Use only grounded air and fluid hoses. Check equipment and workpiece grounding devices regularly. Resistance to ground must not exceed one megohm.
- Shut down all equipment immediately if you notice static sparking or arcing. Do not restart the equipment until the cause has been identified and corrected.
- Do not smoke, weld, grind, or use open flames where flammable materials are being used or stored.
- Do not heat materials to temperatures above those recommended by the manufacturer. Make sure heat monitoring and limiting devices are working properly.
- Provide adequate ventilation to prevent dangerous concentrations of volatile particles or vapors. Refer to local codes or your material MSDS for guidance.
- Do not disconnect live electrical circuits while working with flammable materials. Shut off power at a disconnect switch first to prevent sparking.
- Know where emergency stop buttons, shutoff valves, and fire extinguishers are located. If a fire starts in a spray booth, immediately shut off the spray system and exhaust fans.
- Shut off electrostatic power and ground the charging system before adjusting, cleaning, or repairing electrostatic equipment.
- Clean, maintain, test, and repair equipment according to the instructions in your equipment documentation.
- Use only replacement parts that are designed for use with original equipment. Contact your Nordson representative for parts information and advice.

Halogenated Hydrocarbon Solvent Hazards

Do not use halogenated hydrocarbon solvents in a pressurized system that contains aluminum components. Under pressure, these solvents can react with aluminum and explode, causing injury, death, or property damage. Halogenated hydrocarbon solvents contain one or more of the following elements:

Element	Symbol	Prefix
Fluorine	F	“Fluoro-”
Chlorine	Cl	“Chloro-”
Bromine	Br	“Bromo-”
Iodine	I	“Iodo-”

Check your material MSDS or contact your material supplier for more information. If you must use halogenated hydrocarbon solvents, contact your Nordson representative for information about compatible Nordson components.

7. Action in the Event of a Malfunction

If a system or any equipment in a system malfunctions, shut off the system immediately and perform the following steps:

- Disconnect and lock out system electrical power. Close hydraulic and pneumatic shutoff valves and relieve pressures.
- Identify the reason for the malfunction and correct it before restarting the system.

8. Disposal

Dispose of equipment and materials used in operation and servicing according to local codes.

Section 2

Description

Section 2
Description

1. Introduction

See Figure 2-1. The Pro-Flo system automates the application of sealants and adhesives. The system includes a Pro-Flo gun and controller that work in conjunction with a robot and robot controller.

The Pro-Flo controller uses signals from the robot controller and other sensors to control the gun dispensing rate. A constant bead size is maintained by adjusting the dispensing rate for changes in robot speed, material viscosity, and material delivery pressure.

Functions

The Pro-Flo Controller:

- maintains a consistent dispensed volume even as the viscosity of the material varies
- learns the shear-thinning effects of the material and automatically adjusts the dispensing rate
- displays recovery procedures if operation faults are generated by the controller or gun
- communicates faults to the robot controller.

Functions *(contd)*

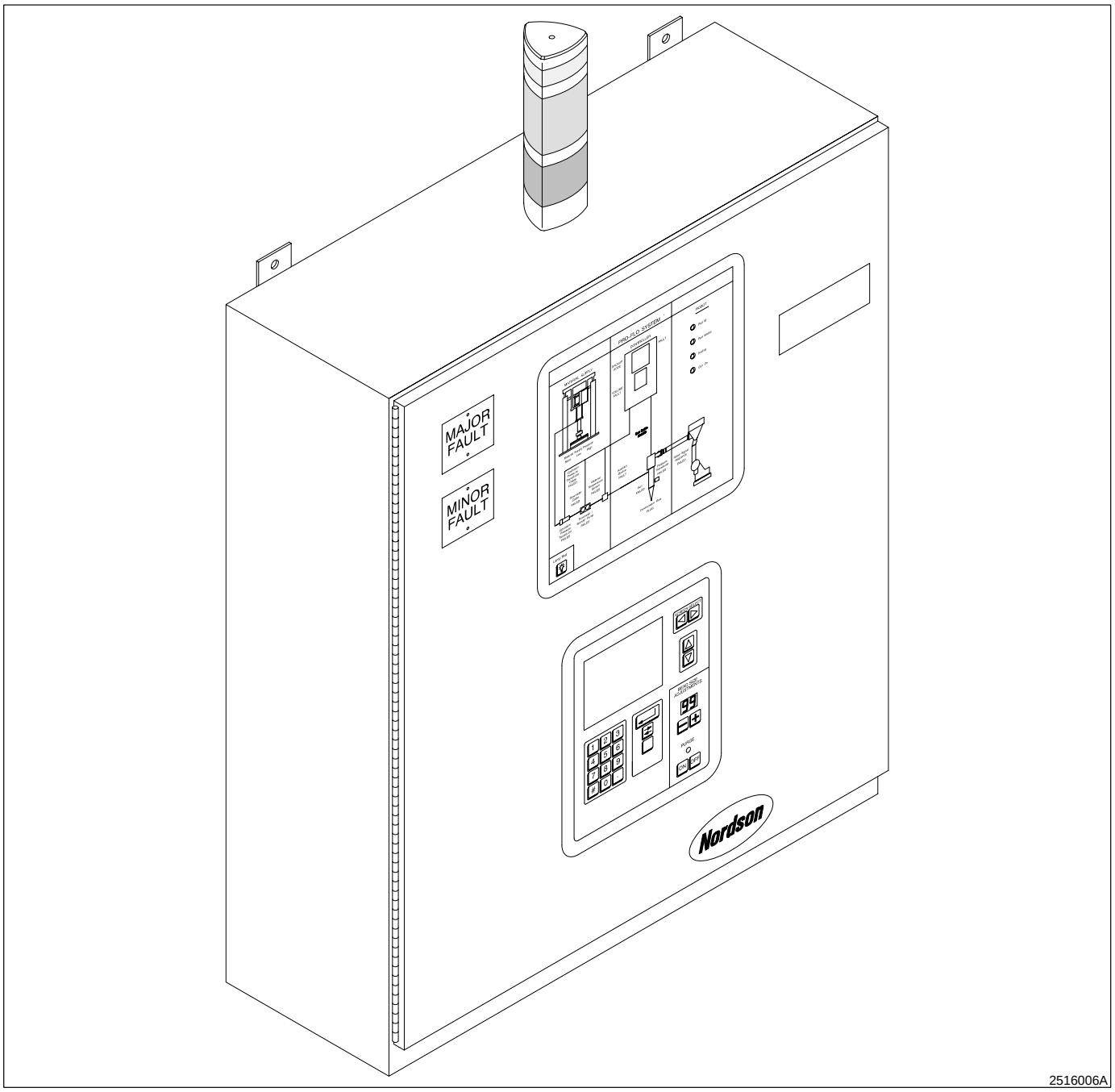


Fig. 2-1 Pro-Flo Controller

Components

The following are components of the Pro-Flo Controller.

1. A software program configured by Nordson Corporation for your application
2. A flowmeter assembly, which includes a flowmeter, an upstream pressure transducer, and a resistance temperature detector (RTD)
3. Electrical cables for connecting the controller to the gun, robot controller, and optional equipment

Monitoring Capabilities

In addition to controlling an air-spray (compact) or extrude (dispensing) gun, the controller can be used to monitor or control the following system components:

- material cut-off (MCO) module (extrude guns only)
- air-spray proportioning valve (air-spray guns only)
- flowmeter
- upstream pressure transducer
- material supply regulator

2. Theory of Operation

The robot controller outputs an analog (tool-speed) signal that is proportional to the robot speed. The controller uses this signal to adjust the dispensing rate of the gun. When the robot speeds up, the gun dispenses material faster, and when the robot slows down, it dispenses material slower.

The controller continuously monitors the volume of material dispensed and automatically adjusts the dispensing rate to maintain a constant bead size. The controller compensates for batch-to-batch variation in material and shear-thinning effects.

A second analog signal is output by some robot controllers and can be used to control the proportioning valve pressure in air-spray guns. More or less atomizing pressure is supplied from the proportioning valve when the robot speeds up and slows down, respectively. Precise bead-size control is achieved with independent control over the dispensing rate and delivery pressure.

Alarms

The controller alerts the operator when a fault occurs by lighting the alarm tower and flashing a signal on the diagnostic panel. The software provides a description of the fault, the appropriate corrective action to take, or how to contact Nordson Corporation for assistance. The operator has the option of stopping the system to correct the fault, or running the system in backup mode and correcting the fault later.

Optional Feature

An optional feature of the controller logs statistical process control (SPC) data. A serial port interface can be used to transfer SPC data to a personal computer or disk drive. Data can be received by a computer running the Nordson DataLink program, which is sold separately.

Section 3

Installation

Section 3
Installation

WARNING: Allow only qualified personnel to perform the following tasks. Follow the safety instructions in this document and all other related documentation.

1. Introduction

Unpack the Pro-Flo controller and inspect it for dents, scratches, corrosion, or other physical damage. If there is any visible damage, call your Nordson Corporation representative immediately.

2. Mounting Dimensions and Clearance Requirements

Mounting dimensions and clearance requirements for the controller are shown in Figures 3-1 and 3-2. Mount the controller as close to the robot controller as possible.

2. Mounting Dimensions and Clearance Requirements (contd)

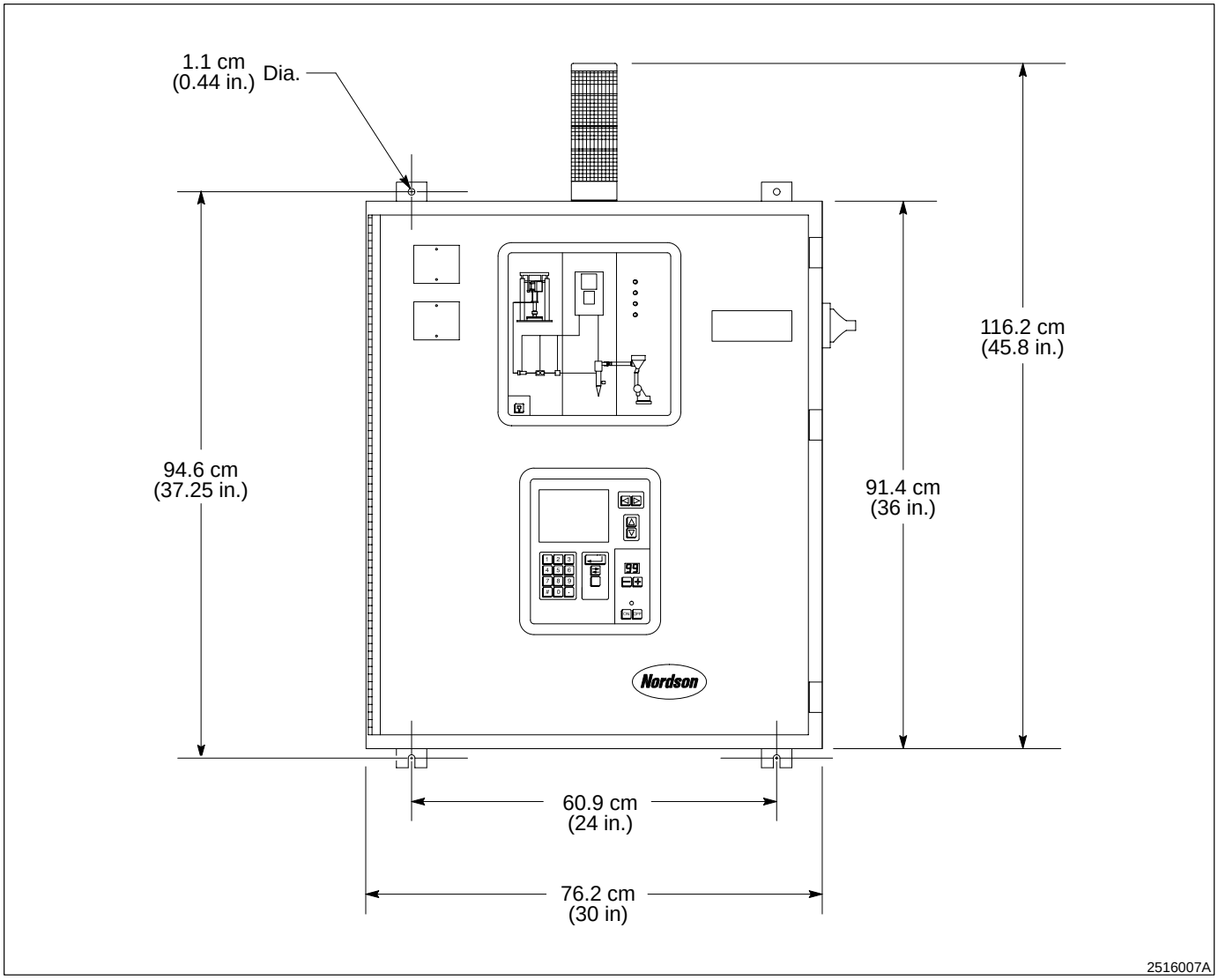


Fig. 3-1 Mounting Dimensions

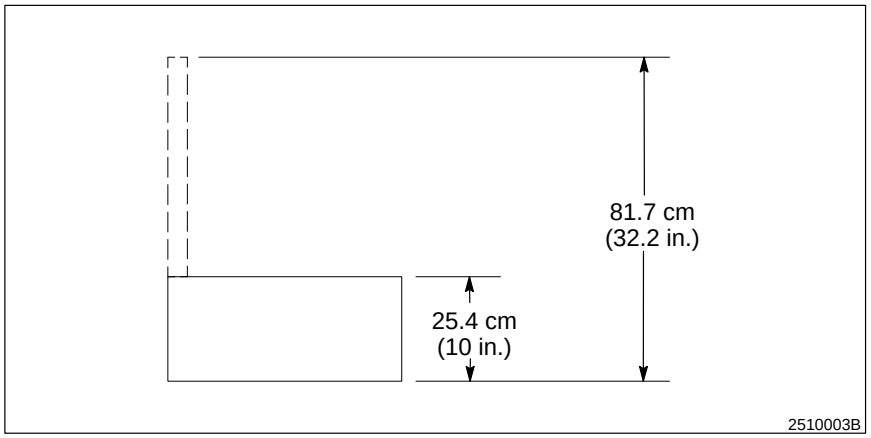


Fig. 3-2 Clearance Requirements

3. Electrical Connections

NOTE: Refer to the system drawings included with the unit for Pro-Flo guns used in your application.

Requirements

Follow these requirements when installing electrical connections to the Pro-Flo controller.

- Install a dedicated power supply for the controller to provide safe operation and to reduce interference from electrical noise.
- Install all electrical connections to local code.
- Install a locking disconnect switch or breaker in the service line ahead of any electrical equipment.

Connecting the System

WARNING: Risk of electrical shock. The robot controller contains electrical potentials that can be fatal. Disconnect and lock out electrical power before opening the robot controller enclosure and making connections.

See Figures 3-3 and 3-4. The standard controller interface is supplied to customers installing new Pro-Flo systems. Use the cables supplied to connect the Pro-Flo controller to the robot controller, Pro-Flo gun, and flowmeter assembly.

NOTE: When connecting cables between the gun (6) and controller (2), make sure there is enough slack to allow robot and gun movement. Use an extension gun cable (5) if necessary.

NOTE: Each cable plug has a key that matches a notch in the receptacle in the correct orientation.

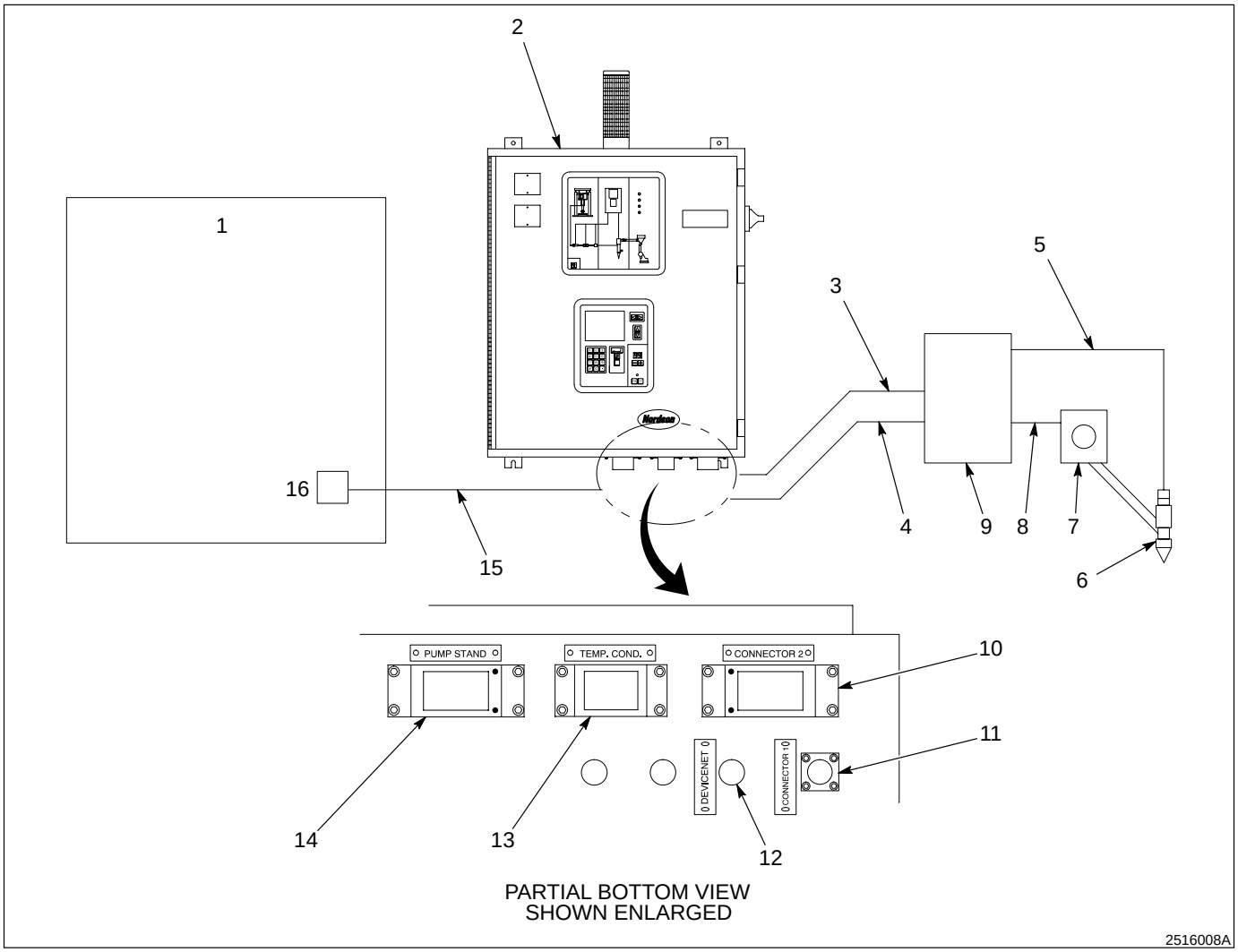


Fig. 3-3 Standard Cabling Connections

1. Robot Controller
2. Pro-Flo controller
3. Gun control cable
4. Flowmeter cable
5. Extension gun cable
6. Gun
7. Flowmeter
8. Extension cable
9. J-Box
10. Flowmeter connector
11. Gun connector
12. DeviceNet connector
13. Temperature condition connector
14. Pump stand connector
15. DeviceNet cable
16. DeviceNet connector on robot controller

Connecting the System *(contd)*

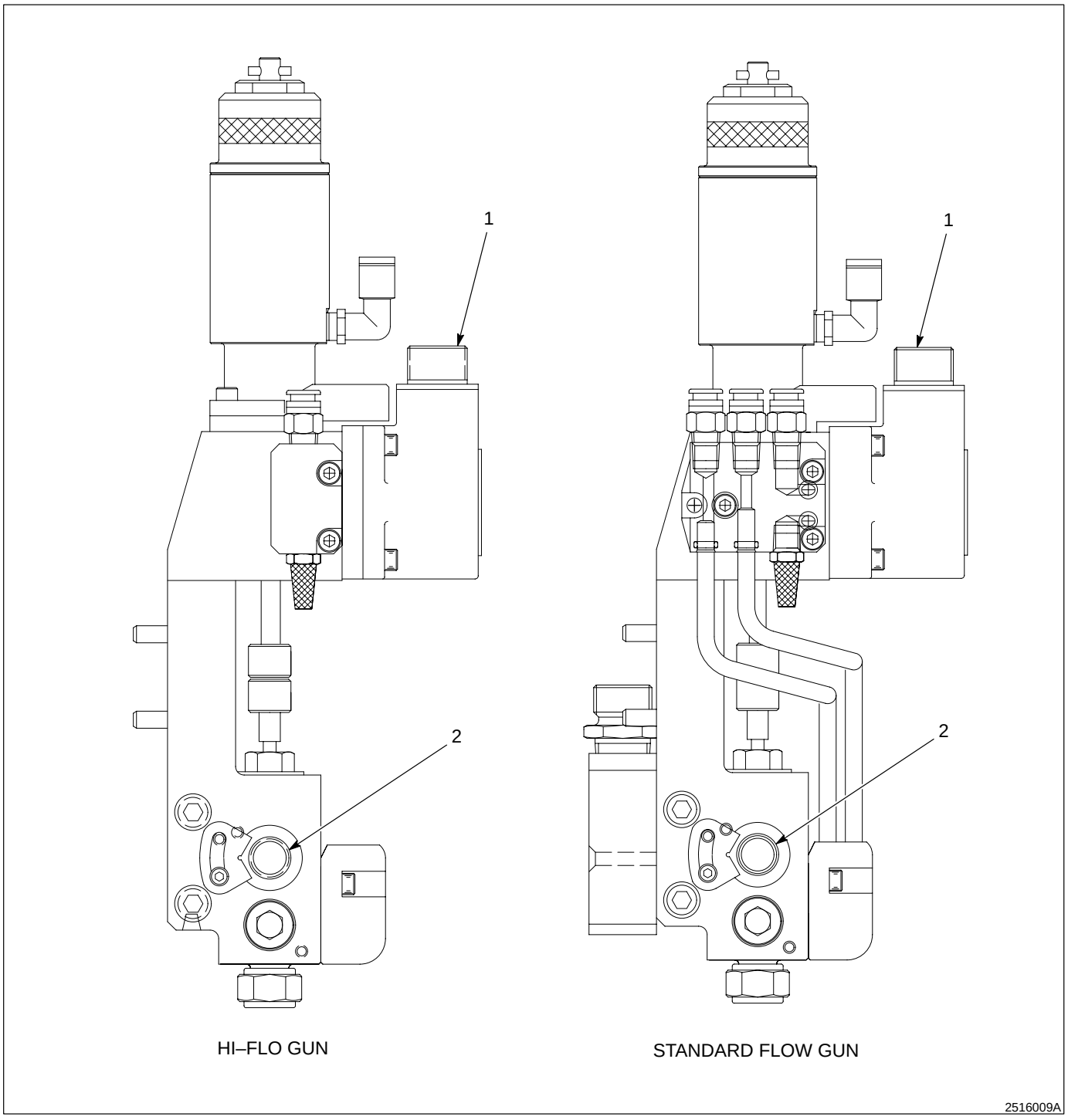


Fig. 3-4 Typical Pro-Flo Guns

1. Gun control cable receptacle
2. Material inlet

Follow these procedures to make the correct cable connections in the Pro-Flo system.

DeviceNet/ Robot Interface Connection

See Figure 3-3. Connect the robot interface cable to the DEVICENET receptacle.

Gun Connections

NOTE: See the system drawings included with the unit for Pro-Flo guns used in your application.

NOTE: When connecting cables between the gun and the J-Box (9), make sure there is enough slack to allow robot and gun movement. Use as many gun control cables as necessary.

1. See Figure 3-3. Connect the gun control cable (3) to the CONNECTOR1 receptacle.
2. Connect the free end of the gun cable to the J-Box (9).
3. Connect an extension gun cable (5) from the J-Box to the Pro-Flo gun receptacle (Figure 3-4 (1)) of your dispensing or compact gun.
4. Connect as many extension gun cables from the J-Box to the dispensing gun or compact gun to allow for robot and gun movement.

Flowmeter Connections

1. See Figure 3-3. Connect the flowmeter cable (4) to the CONNECTOR2 receptacle.
2. Connect the free end of the flowmeter cable (4) to the J-Box (9).
3. Connect the extension cable (8) from the J-Box (9) to the flowmeter (7).

4. Fluid Connections

Make the following fluid connections:

1. See Figure 3-4. Connect the material supply hose from the drum unloader to the material inlet.

2. Connect a material supply hose from the material outlet to the material inlet (2) of your dispensing or compact gun.

5. Configuring your Robot Controller

Fault codes are documented in the *Specifications* section.

Analog #1

See Figure 3-5. Configure your robot controller to vary the analog #1 (or tool speed) signal from 0 to 10 Vdc over the full range of robot speed.

1. Determine the highest and lowest robot speeds to be used in production.

2. Configure the robot controller to output an analog #1 signal of +10 Vdc when the robot is moving at, or slightly above maximum speed.

3. Configure the robot controller to output the analog #1 signal of 0 Vdc when the robot is stationary.

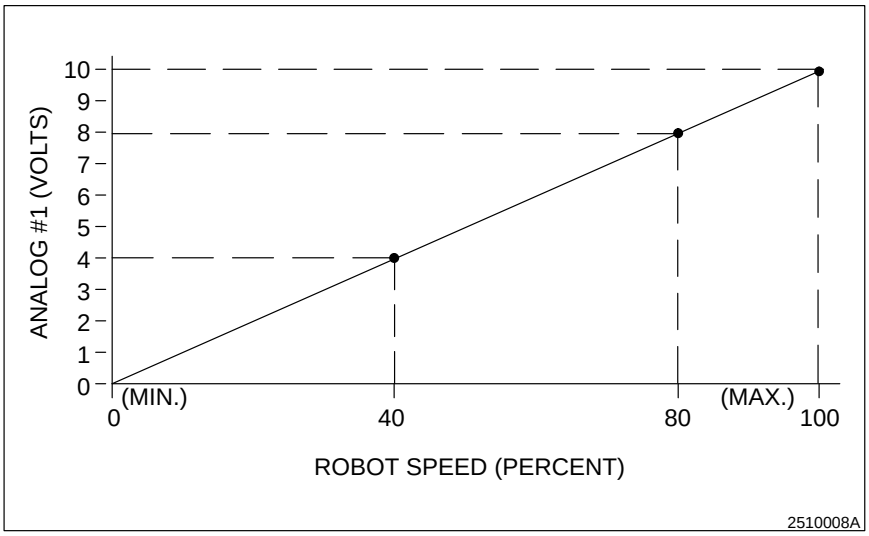


Fig. 3-5 Relationship Between Analog #1 Signal and Robot Speed

NOTE: Figure 3-5 presents an example of the approximate relationship between robot speed and analog #1 voltage as a guide for the operator. A robot speed of 80% corresponds to 8 Vdc. A robot speed of 40% corresponds to 4 Vdc.

Analog #2

If your robot supplies the optional analog #2 (or tool speed #2) signal and you are using an air-spray gun, more precise control over atomizing air pressure is possible. The controller controls the proportioning valve feeding air to the gun to adjust atomizing air pressure for robot speed. Establish the relationship between the signal and the pressure supplied to the proportioning valve.

Configure the robot controller to output an analog #2 signal of 2, 4, 6, and 8 Vdc when the pressure supplied to the proportioning valve is 1.38, 2.76, 4.14, and 5.52 bar (20, 40, 60, and 80 psi), respectively.

6. Setting Timing Sequences

Adjust the timing sequence of output signals from the robot controller to suit the Pro-Flo controller. Refer to your robot controller manual for procedures to set the signal timing sequences.

See Figure 3-6.

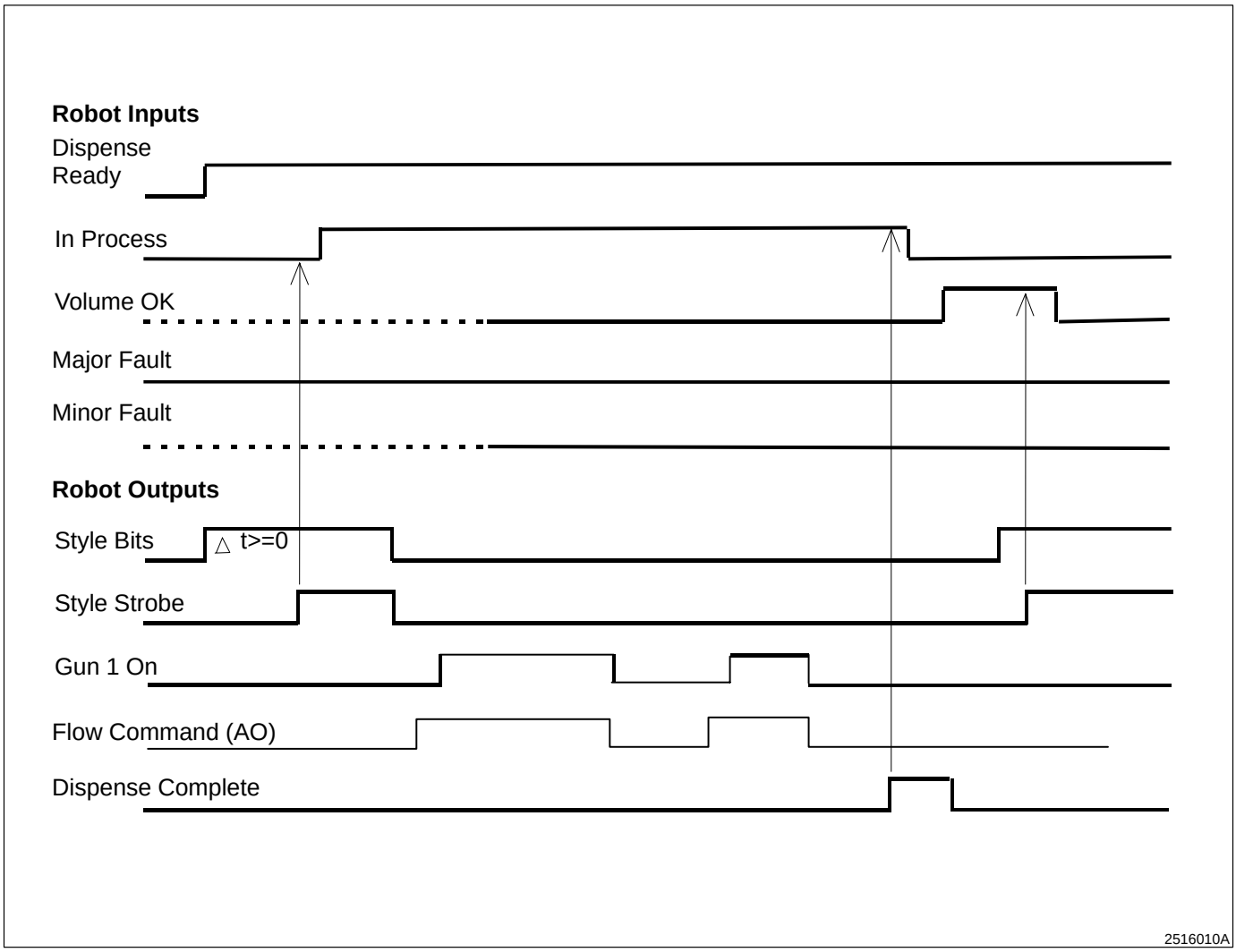


Fig. 3-6 Normal Dispensing Cycle — Base Level Common Interface

Section 4

Operation

Section 4
Operation

WARNING: Allow only qualified personnel to perform the following tasks. Follow the safety instructions in this document and all other related documentation.

1. Introduction

Follow the instructions given in this section to operate your Pro-Flo controller. The controller has been configured by your Nordson Corporation representative. If the configuration needs to be modified, use the Pro-Flo configurator software.

NOTE: Before operating the controller, make sure the robot has been taught the proper tool path. Refer to the Robot controller manual.

1. Introduction (contd)

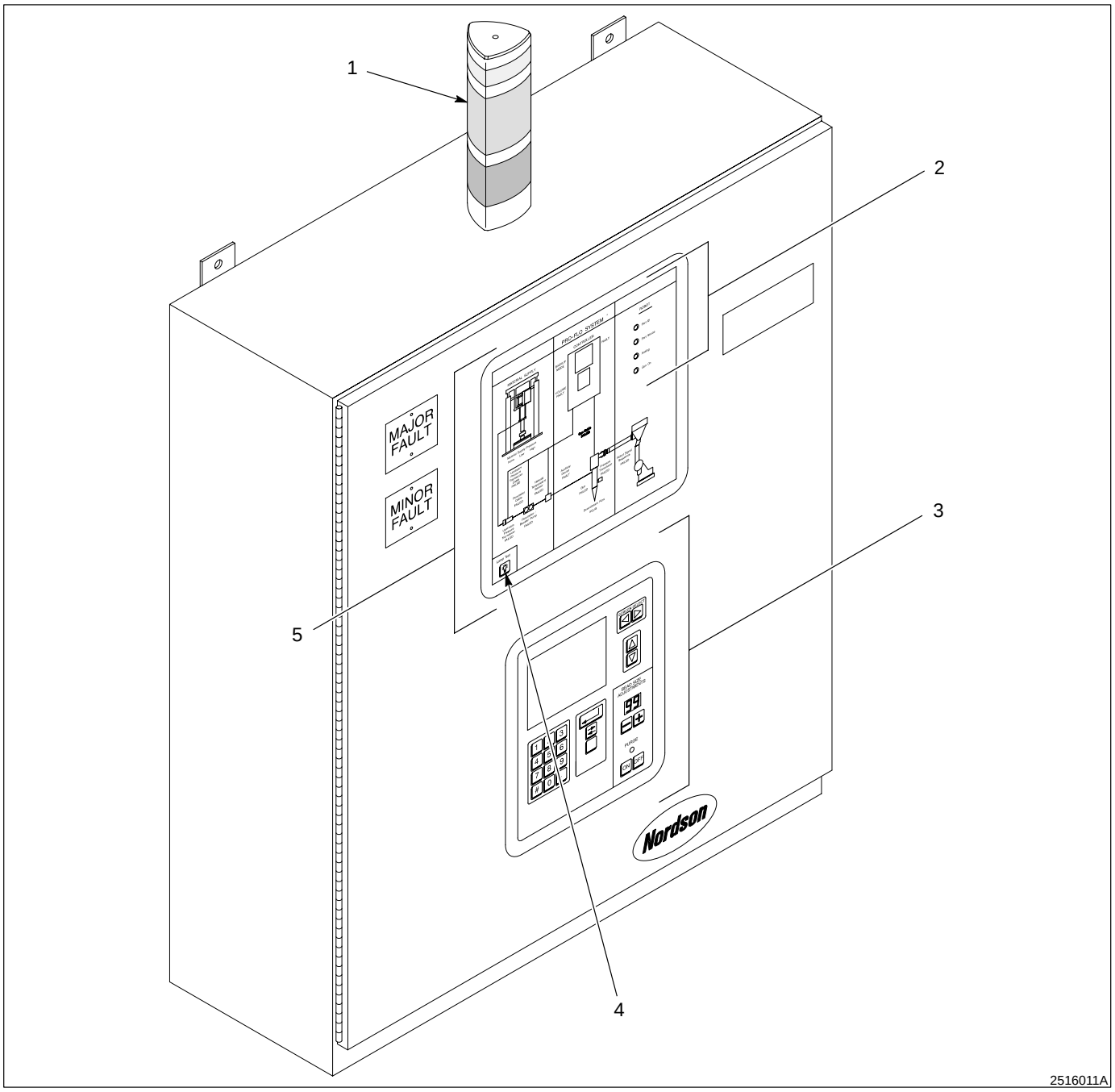


Fig. 4-1 Pro-Flo Controller User Interface

1. Alarm tower
2. Robot signal indicators
3. Operator keypad
4. LAMP TEST key
5. Diagnostic panel

2. User Interface

See Figure 4-1.

Use the operator keypad (3) to select and define production parameters. The keys and indicators on the operator keypad panel are described in Table 4-1.

See Figure 4-2.

Table 4-1 Controls and Indicators on the Controller

Item	Command Keys	Function
1	Screen select	highlights screen selection from top menu bar shown on display
2	Up and down arrow	highlights prompt from screen
4	+/-	adjusts bead size up or down
6	Purge ON/OFF	starts or stops gun from purging
7	CLR	clears numeric values
8	Toggle	toggles between on/off or yes/no
9	Enter	activates screen selection or enters numeric value typed at prompt
10	Numeric	types numeric values
Item	**Indicator Keys**	**Function**
3	Bead size	displays bead size. Bead size is an arbitrary number between 1 and 99. The current bead size is displayed on the bead size indicator. Use the bead adjustment keys to increase or decrease the bead size.
5	Purge	lights when gun is open for purging. Purge the gun before use to remove air from the material supply hose and nozzle. Press the ON key to begin purging. The purge indicator lights while the gun is open. Purging will stop after the purge time has elapsed. Otherwise, press the OFF key to stop purging immediately.
11	Display	displays top menu bar and currently selected screen
12	Screen selection menu	displays available selections

3. Screen Menus

See Figure 4-2. The screen selection menu (12) is displayed across the top line of the display (11). Use the screen select keys (1) to highlight one of four screen choices: VOLUME, HELP, TEST-POINTS, or SET-UP. Use the up or down arrow to highlight the prompts from the screen.

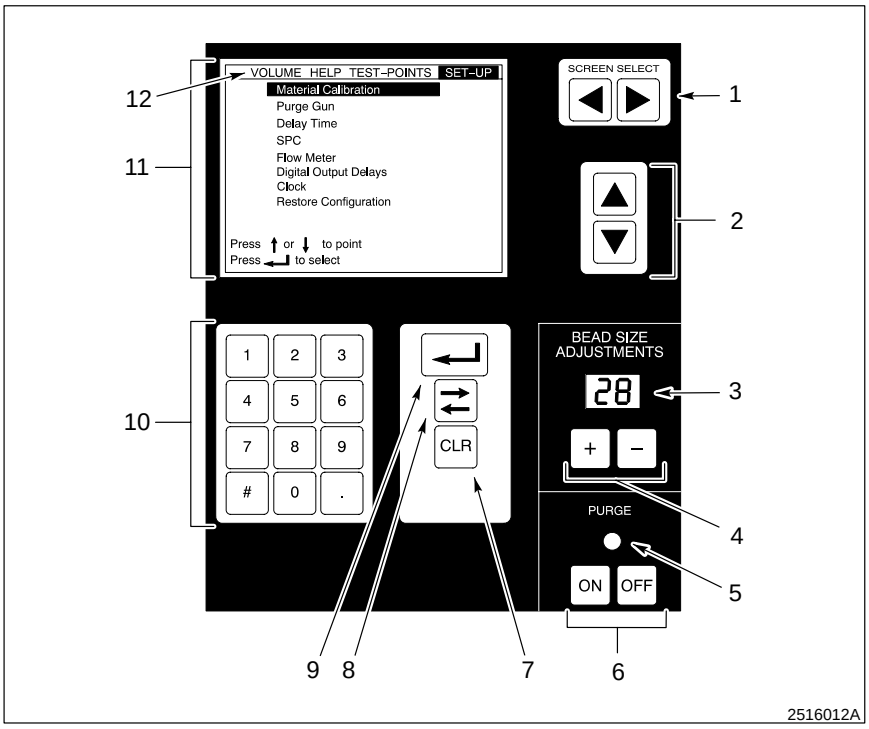


Fig. 4-2 Operator Keypad

1. Screen select keys
2. Up and down arrow keys
3. Bead size indicator
4. Bead size adjustment keys
5. Purge indicator
6. Purge ON/OFF keys
7. Clear key
8. Toggle key
9. Enter key
10. Numeric keypad
11. Display
12. Screen selection menu

VOLUME

See Figure 4-3. View the VOLUME screen during production to monitor material dispensing characteristics. For each part run, the VOLUME screen displays the time, part identification, bead size, volume set point, actual volume dispensed, and whether the volume is within the customer-set range.

NOTE: If the volume is within the customer set range, the OK column is left blank. If the volume is not within the customer set range, NO is displayed in the OK column.

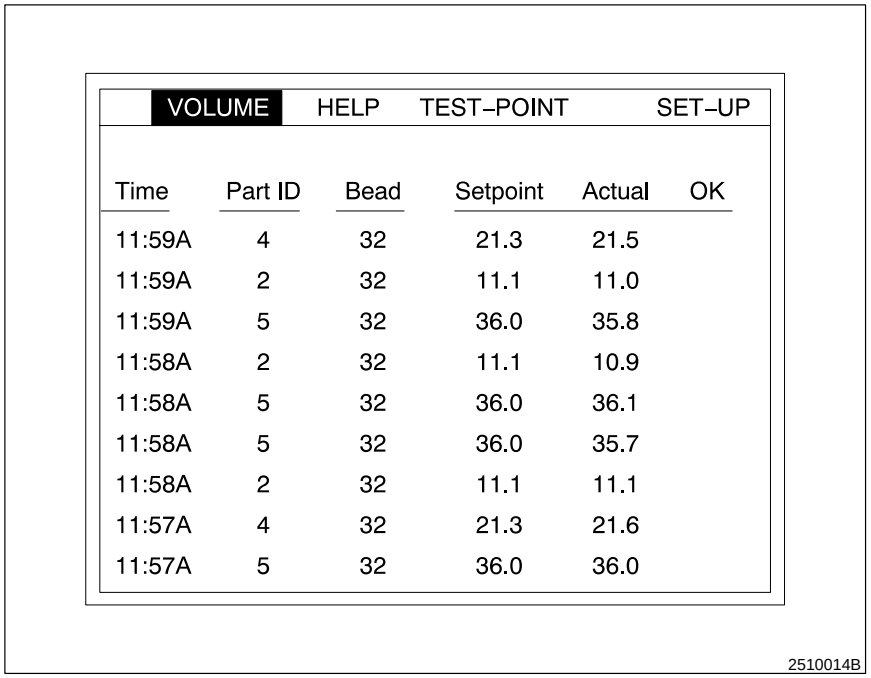


Fig. 4-3 VOLUME Screen

HELP

See Figure 4-1. If a fault is detected during operation, the alarm tower (1) red light turns on and the type of fault is indicated on the diagnostic panel (5).

Use the up and down arrow keys to display an explanation of the fault and the suggested corrective action. One example of a HELP screen is shown in Figure 4-4.

NOTE: Press the LAMP TEST key occasionally to test the lights on the diagnostic panel.

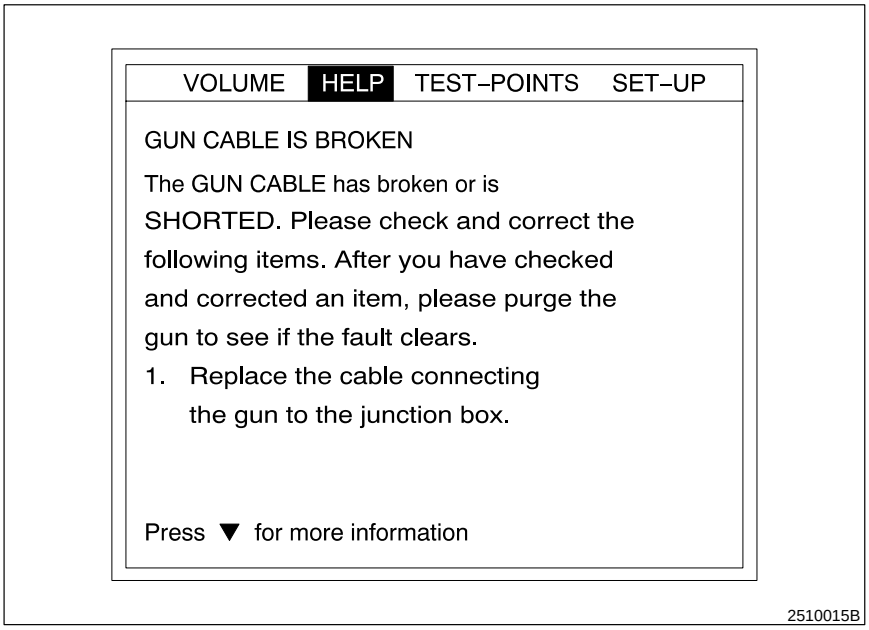


Fig. 4-4 HELP Screen

TEST-POINTS

The TEST-POINTS screen is reserved for use by Nordson Corporation field service engineers.

SET-UP

See Figure 4-5. Use the SET-UP screen to set the dispensing rate parameters. Refer to Table 4-2 for a description of each parameter.

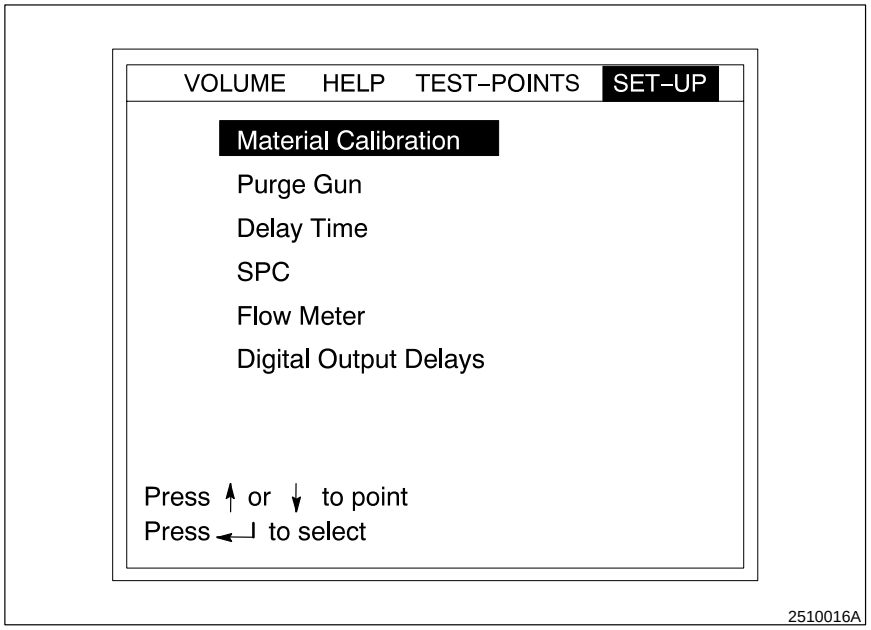


Fig. 4-5 SET-UP Screen

SET-UP *(contd)*

Table 4-2 Set-Up Parameters

Parameter	Function
Material Calibration	**NOTE:** Material is dispensed during this operation. Place a waste bucket under the gun. Do not allow the robot to move. Run a material calibration after the controller is installed and whenever you change the type of dispensing material. Material calibration allows the controller to learn the material's shear thinning properties. When this prompt is selected, the controller runs an automatic routine for up to 5 minutes while dispensing material.
Purge Gun	The Dispense Time determines how long the gun stays open each time the Purge ON button is pressed. Enter a Dispense Time from 1 to 60 seconds.
Delay Time	The Tool Speed and gun delay times determine how fast the controller reacts to signals received from the robot controller. Sometimes delays are necessary to prevent the controller from reacting more quickly than the robot. These delays are in milliseconds (msec). The Tool Speed parameter delays the controller's reaction to robot motion. Enter a Tool Speed delay from 0–500 msec. The Gun On and Gun Off parameters delay the controller's reaction to the gun-on and gun-off signals from the robot controller. These parameters adjust the start and stop time of material dispensing. Enter Gun On and Gun Off delays from 0–500 msec.
Statistical Process Control (SPC) (Optional)	Use the SPC screen to clear data from the SPC queue or to download it to a PC using the Nordson DataLink program. Refer to the *Nordson DataLink User's Guide* for more information.
Flow Meter	When a new flowmeter is installed, enter its flow rate (or K-value) in counts/liter. The K-value is stamped on the side of the flowmeter body.
Digital Output Delays	If your system requires digital output delays, your local Nordson Corporation representative will configure it. The on-screen prompts will alert you of any needed adjustments.
Clock	Set the time and date is set using this function during initial startup. The SPC feature utilizes this parameter by time and date stamping each cycle stored in memory.
Restore Configuration	Restores the latest configuration parameters in the event of a memory loss.

4. Initial Set-Up

Use this procedure to make one-time adjustments to the controller before beginning production for the first time.

When the controller is turned on, it performs a self-test routine to verify proper operation. After the routine is completed, begin this procedure to achieve the proper bead size and shape.

1. See Figure 4-2. Use the screen select keys (1) to highlight SET-UP on the top menu bar of the display (11).

2. Use the up and down arrow keys (2) to highlight the Flow Meter prompt. Enter the K-value stamped on the side of the flowmeter body.

NOTE: Material is dispensed during this operation. Place a waste bucket under the gun.

3. Run a material calibration. Use the up and down arrow key (2) to highlight the Material Calibration prompt. The controller runs an automatic routine for up to 5 minutes while dispensing material.

4. Use the bead size adjustment keys (4) to set the bead size, which is displayed on the bead size indicator (3).

NOTE: Bead size is a number between 1 and 99. Bead size has no units; it is simply a relative number.

Testing Your Set-Up Parameters

Run a test to determine if your set-up parameters are correct. Follow these procedures to achieve a bead of the correct size and shape.

1. Position the part under the gun and begin material dispensing from the robot controller.

2. See Figure 4-2. If the bead is too small, adjust it to a higher number with the bead adjustment keys (4). If the bead is too big, adjust it to a lower number.

3. If dispensing did not start or stop at the correct time, adjust the Gun On or Gun Off delay times. See Figure 4-5. From the SET-UP screen, highlight the Delay Time prompt. Enter Gun On and Gun Off delays from 0–500 msec.

Testing Your Set-Up Parameters (contd)

NOTE: Improper robot programming may be the cause of the incorrect dispensing start and stop times.

4. Repeat steps 1 through 3 until you achieve a bead of the correct size and shape.

5. Record the bead size and the part ID. Return to this bead size every time this type of part is run.

NOTE: Once set correctly, the delay times should not need readjusting as other types of parts are run.

6. Repeat steps to determine the desired bead size for every type of part to be run.

5. Using Configurator

Use these procedures to install and operate the Configurator program.

Description

The Nordson Pro-Flo II configuration utility program (or Configurator) is used to create, read, and save configuration parameters of the Nordson Pro-Flo II Digital Controller. The program runs on IBM compatible personal computers.

Configurator is distributed with two batch files called SAVE and LOAD. These batch files are used to transfer files between the PC and controller. LOAD transfers files from the PC to the controller, and SAVE transfers files from the controller to the PC.

Follow the operating procedure in this manual to set the desired configuration.

Requirements

To run the Configurator, you must have an IBM compatible computer with at least:

- 386 microprocessor
- 640 kb of RAM
- DOS operating system, version 3.0 or later
- One floppy drive and one hard drive
- RS-232 serial communications port and cable

Installation

Follow the procedure in this section to install the Configurator program. All commands are typed at the DOS prompt.

1. Create a directory on your PC's hard drive to store the Configurator program. For example, to create a new directory called CONF, type:

   MKDIR C:\CONF

2. Copy all files distributed on the program disk to the hard drive directory. If the program disk is in floppy drive A, type:

   COPY A: *.* C:\CONF

   The installation is now complete.

3. After installing the Configurator program, remove the program disk from the floppy drive and store it in a safe place.

Operation

Follow the procedure in this section to use the Configurator program. All commands are typed at the DOS prompt.

1. Make the Configurator program directory the active current directory; type:

   CD C:\CONF

2. Start the program; type:

   CONFIG

   See Figure 4-6. The copyright screen is displayed.

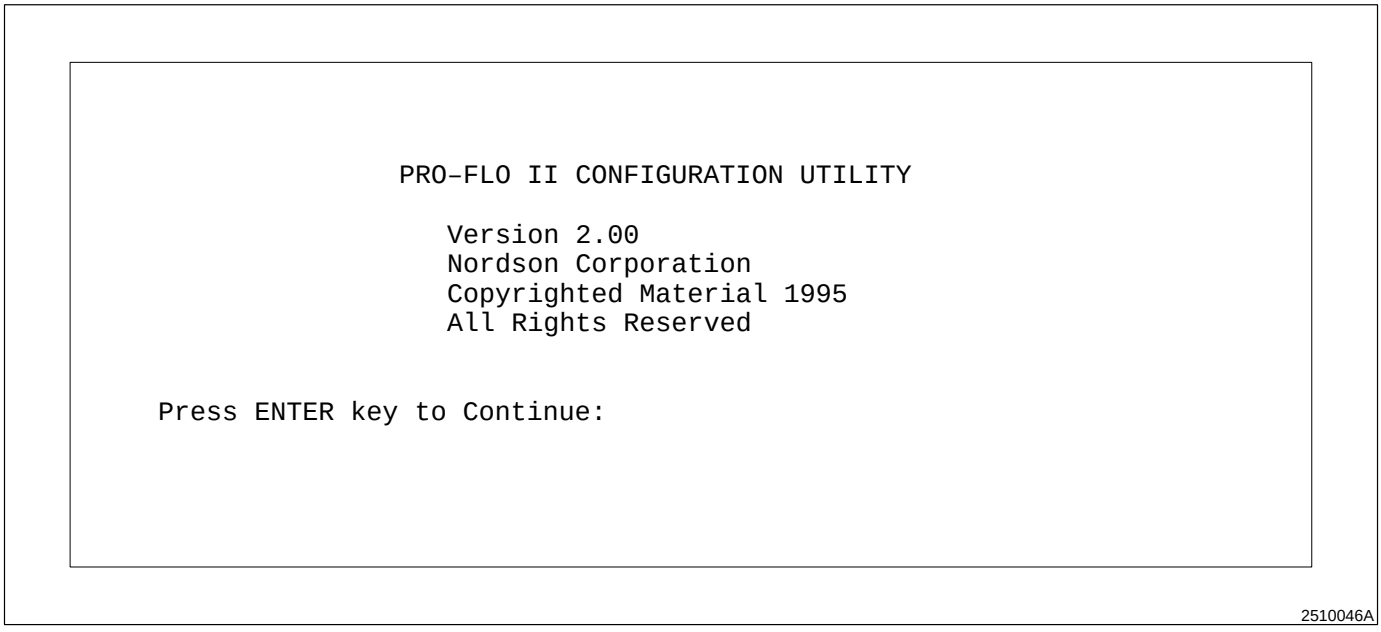


Fig. 4-6 Copyright Screen

***Operation** (contd)*

3. Press **ENTER** to continue to the file selection screen.

4. At the **file:** prompt, type the name of the file you want to create or modify. For example, to modify the default configuration file supplied by Nordson Corporation, type:

   DEFAULT.CFG

NOTE: If you want to modify an existing file, it must be located in the currently active directory.

NOTE: File names must have no more than eight characters, and should not contain periods, spaces, or an extension. The extension ".CFG" will be added automatically.

5. Press **ENTER**. The Configurator program reports the file across the bottom of the screen. This report includes the name of the file, the version of Configurator program used to create it, and the date and time the file was modified last.

```
File:  DEFAULT.CFG Information
file is from Configurator version 2.00
date = 07/28/95                          time = 09:39:44
Press ENTER key to Continue:
```

6. See Figure 4-7. Press **ENTER** to display the top-level menu.

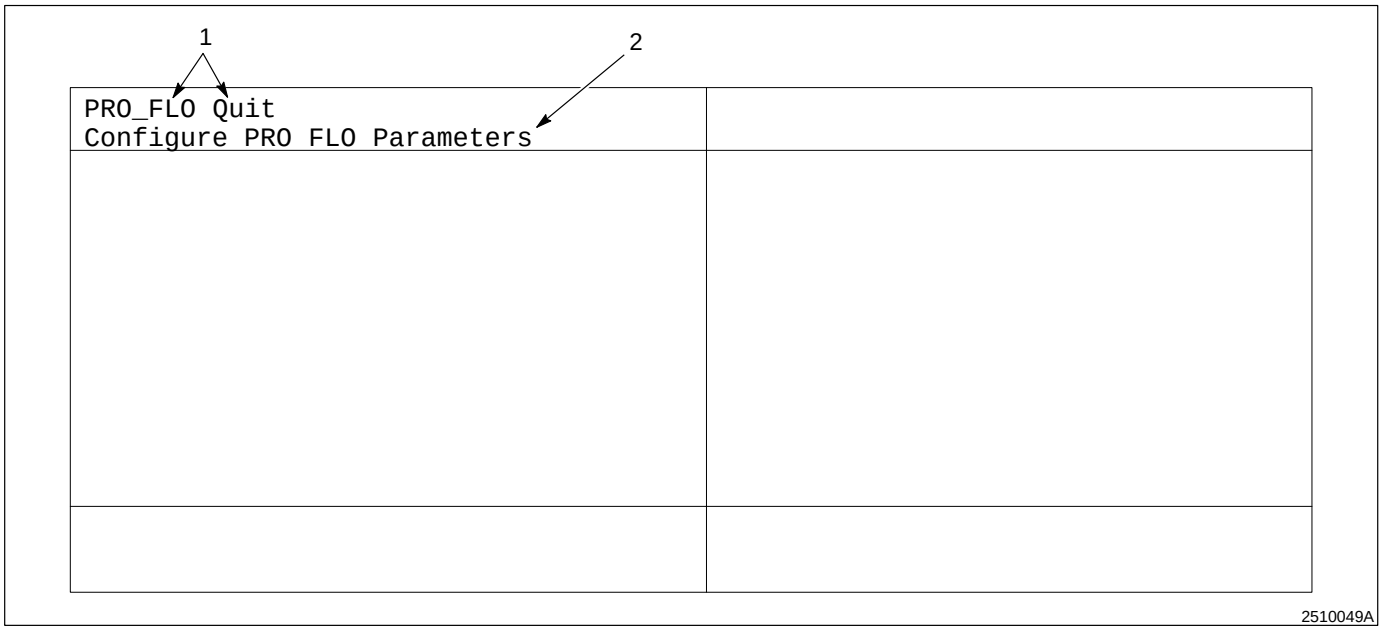


Fig. 4-7 Top-Level Menu

1. Screen selection menu
2. Screen description

The screen selection menu (1) is across the top line of the top-level screen. Use the arrow keys to highlight your selection. A blinking block cursor indicates that the screen is currently highlighted.

The screen description (2) gives a one-line explanation of the highlighted screen. To bring up the highlighted screen, press **ENTER**.

NOTE: A highlighted selection is indicated by a blinking block cursor positioned over the first character.

Quitting

To change an incorrect file name, or to quit the program:

1. Highlight the Quit command and press **ENTER**.

   See Figure 4-8. The program prompts you to save or discard any changes.

2. Type “Yes” or “Y” to save the changes,

   OR

   Type “No” or “N” to discard the changes.

NOTE: You can only save changes to the file that you opened.

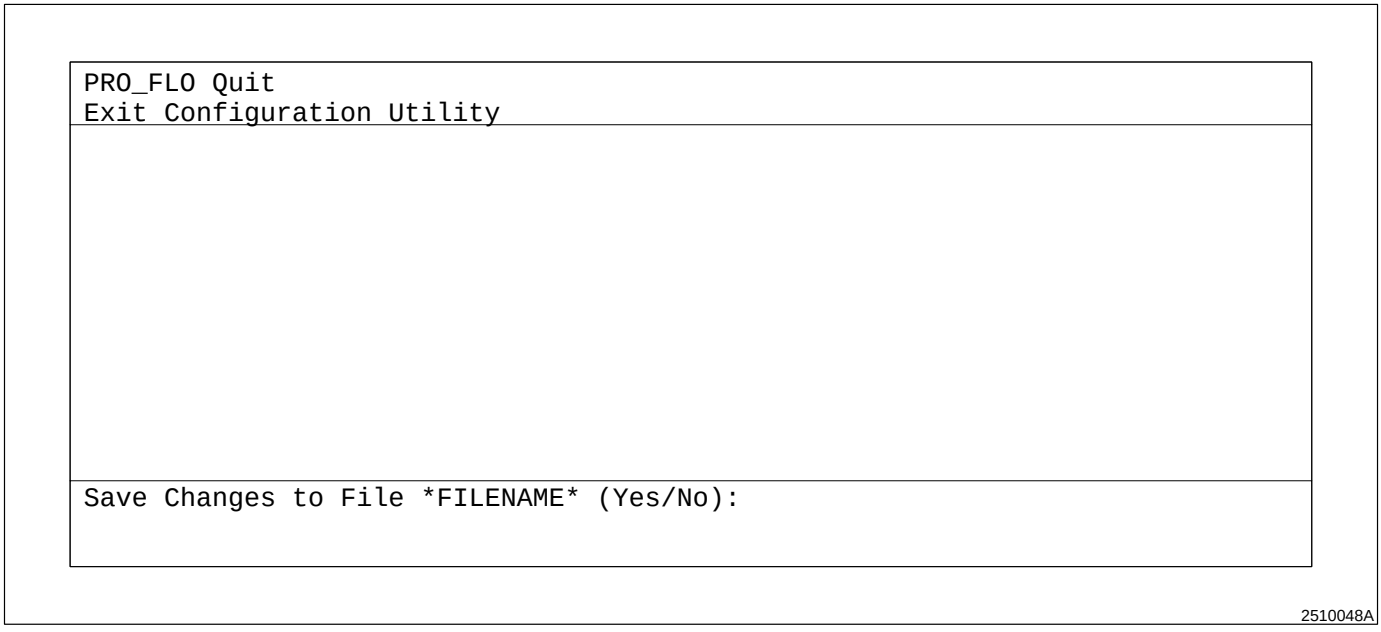


Fig. 4-8 Saving Changes

Creating a New Configuration File

New configuration files can be created using a previously saved configuration as a basis for the new file.

1. Make the Configurator program directory the active current directory; type:

   CD C:\CONF

2. Create the new configuration file, type:

   COPY DEFAULT.CFG NEWFILE.CFG

3. Change the parameters, as described in the next section, if desired.

Changing Parameters

This procedure describes how to change the setup parameters of an existing file.

1. Start Configurator and open the desired file. Refer to *SetUp Using Configurator* for instructions on how to do this.

2. Highlight the PRO-FLO command.

3. Press **ENTER**. The Pro-Flo data entry screen is displayed.

```
PRO_FLO Parameters, Data Entry Table
<ESCAPE = EXIT>

Gun Delays:                          Dispense Volume:
 Analog Delay(1–500msec):            Major High Volume Alarm (%over): 20
 GunOn Delay(1–5,000msec):           Minor High Volume Alarm (%over): 10
 GunOff Delay(1–5,000msec):          Major Low Volume Alarm (%under):20
Digital Outputs:                     Minor Low Volume Alarm(%under):10
 Output Number(0–3): 0               System Parameters:
 Output Name:                          Language (Eng,Ger,Fren):ENGLISH
 On Delay(1–5,000msec): 1              Voluume Display (cc,oz):cc’s
 Off Delay(1–5,000msec): 1             Clock Format (24,12hr): 24 Hours
Flowmeter Counts per Liter:            Pressure Units (psi,Bar):PSI
 Counts(1–1,000,000): 1000           Bead Options:
Volume Output: :                       Bead size: 49
 Volume(1–1,000,000) : 1               Bead Option: FULL
Material Purge Parameters              Limited Range(1–50%):25
 Purge Time(1–60sec): 1                Pasword(0–999): 123

Select Configuration Name (max 8 digits); ENTER KEY for DEFAULT:
```

2516013A

Fig. 4-9 Data Entry Screen

4. See Figure 4-9. Use the up or down arrow key to highlight the desired parameter.

NOTE: If your keyboard's arrow keys are located on the numerical keypad, make sure the NUM LOCK key is off before using the arrows.

NOTE: The help box at the bottom of the screen explains each parameter as it is highlighted.

5. To change the value of a numerical parameter, highlight it and enter a number from the keyboard.

   OR

   If the prompt requires a text value, use the right and left arrow keys to scroll through the list of valid values. For example, the parameter *Language (Eng,Ger,Fren)* has three valid values: ENGLISH, GERMAN, and FRENCH.

NOTE: The range of valid values for each entry is shown as part of the prompt. If you enter a number that is too high, the highest valid number will be displayed. If you enter a number that is too low, the lowest valid number will be displayed.

6. Once you make the correct entry, move to another parameter by pressing the up or down arrow key.

NOTE: You do not need to press the ENTER key after typing in a new value. The ENTER key has no effect on the data entry screen.

Saving Changes

After making all of your changes, press the **ESCAPE** key to the top level. Here, you may quit the program and save all changes made. Refer to *Quitting*.

Transferring Files to and from the Pro-Flo Controller

This section describes how to transfer files between the PC and the controller using the LOAD and SAVE programs.

NOTE: LOAD and SAVE use the Nordson DataLink program to transfer files. Please make sure that DataLink is installed in the same directory as Configurator. Refer to the *Nordson DataLink User's Guide* for more information.

1. Connect a serial cable from a serial port on the PC to port2 on the controller.

NOTE: Port2 is the only serial port on the Pro-Flo Controller that can be used to transfer files to and from the Configurator program.

NOTE: Most PCs come with two serial ports: COM1 and COM2. Either of these ports can be used.

2. Change and save configuration options, as desired. Refer to the *Changing Parameters* section for instructions on how to do this.

Transferring a Configuration File from the PC to the Controller

1. Enter LOAD FILENAME COM1

   FILENAME is the name of the file you want to transfer. The extension ".CFG" should not be typed as part of the filename; it will be appended automatically by Configurator.

2. Press **ENTER** to execute the command.

The DataLink transfer screen is displayed on the PC as the file is transferred. Configurator records any warnings or errors generated by the transfer in a file named "trans.log". After the transfer is complete, the contents of this file are displayed.

Transferring a Configuration File From the Controller to the PC

1. Enter SAVE FILENAME COM1

   FILENAME is the name you want to give the file on the PC. This can be either a new, or an existing filename. The extension ".CFG" will be appended automatically by Configurator.

2. Press **ENTER** to execute the command.

NOTE: If you type just LOAD or SAVE at the command prompt, instructions on how to use the commands will appear on the screen.

Maintaining Configuration Files

Keep a copy of the configuration file used on the PC as a backup. You may need to reload it on the controller if parameters are accidentally changed from the controller. You may find it useful to save several configuration files for example, one for each type of part that is run. Follow these tips to maintain your configuration files properly:

- Use the SAVE command to periodically save the configuration from the Pro-Flo controller to a file on the PC, and whenever an option has been changed from the controller. Before making the transfer, rename the old configuration file on the PC so that it may be used as a backup. Copy the new and old files to a floppy disk for backup.

- Before changing a configuration file with Configurator, copy the old configuration file to a different name, such as "OLDCFG". Make the changes to the original file, then transfer it to the controller using the LOAD command.

- Choose a name for the configuration file that indicates what controller it came from. Keep a log of the configuration file name, the date and time it was transferred, and the name of the controller it was transferred from.

- Before upgrading to a new version of EPROM-based Pro-Flo controller software, use the SAVE command to transfer the old configuration file to the PC. Copy the file to a floppy disk for backup.

- After upgrading the EPROM-based software used by the Pro-Flo controller, use the newest version of the Configurator program.

6. Start Up

When the controller is turned on, it performs a self-test routine to verify proper operation. After the routine is completed, begin production.

NOTE: Material is dispensed during this operation. Place a waste bucket under the gun.

1. See Figure 4-2. Purge the gun to remove air from the material supply hose and nozzle by pressing the ON key (6).

   The purge indicator (5) lights while the gun is open. Purging will stop after the purge time has elapsed. Otherwise, press the OFF key (6) to stop purging immediately.

2. If you have changed the type of material since the last production run, perform a material calibration. Use the up and down arrow keys (2) to highlight the Material Calibration prompt on the Set-Up screen. Press the **ENTER** key (9). The controller runs an automatic routine for up to 5 minutes while dispensing material.

3. Check the correct bead size used for the type of part being run. Set the bead size using the bead size adjustment keys (4).

4. Display the VOLUME screen to monitor material dispensing characteristics. Use the screen select keys (1) to highlight VOLUME on the screen selection menu (12) of the display (11).

5. Position the part and begin dispensing from the robot controller.

NOTE: See Figure 4-1. During dispensing, the robot signal indicators illuminate when signals are received from the robot controller. Under normal operating conditions, these lights flash on and off in specific sequence.

7. Backup Mode

If a fault that affects system performance is generated during operation, you may stop production to correct the fault or continue operating in backup mode.

If one of the following faults is detected, you may continue production in backup mode with some sacrifice to bead dispensing characteristics:

- Gun cable
- Gun pressure transducer
- Flowmeter
- Flowmeter cable

If one of these faults is detected, the HELP screen will include a prompt to enter backup mode. When you enter backup mode, the BACKUP MODE indicator on the diagnostic panel lights and the alarm tower light shuts off. You can continue production dispensing without interruption.

Once the fault is corrected, the BACKUP MODE indicator light shuts off after the next part is run or the gun is purged.

Section 5

Troubleshooting

Section 5
Troubleshooting

WARNING: Allow only qualified personnel to perform the following tasks. Follow the safety instructions in this document and all other related documentation.

1. Introduction

This section contains troubleshooting procedures. These procedures cover only the most common problems that you may encounter. If you cannot solve the problem with the information given here, contact your local Nordson Corporation representative for help.

2. Troubleshooting the Pro-Flo Controller

Follow the troubleshooting chart below.

Problem	Possible Cause	Corrective Action
1. Gun not dispensing material	Material supply pressure low	Increase the material supply pressure. Refer to the appropriate drum unloader manual.
	Nozzle blocked	Remove and clean the nozzle. Refer to the appropriate Pro-Flo gun manual.
	Material supply hose blocked	Check material supply hose and unblock it. Refer to the appropriate Pro-Flo gun manual.
	Signals not received from robot in proper timing sequence	Set proper timing sequence. Refer to *Setting Timing Sequences* in the *Installation* section.
	Signals not received from robot controller or sent to gun	Check cable continuity and replace if necessary. Refer to the appropriate Pro-Flo gun manual.
	Spring closures are not retracted	Verify power to controller and controller is on. Verify solenoid supply air to gun is on. Verify air is present at gun and at correct pressure. Replace spring closure assembly if defective.
2. Gun not dispensing material, not opening	Absent or low control air pressure	Check supply air pressure and increase if necessary.
	Stem binding	Remove the trimset valve and loosen the bonnet screw on a packing-type bonnet. Check and replace the stem and bonnet if necessary. Refer to the appropriate Pro-Flo gun manual.

Problem	Possible Cause	Corrective Action
2. Gun not dispensing material, not opening *(contd.)*	Actuator malfunctioning	Replace the actuator. Refer to the appropriate Pro-Flo gun manual.
	Spring closures are not retracted	Verify power to controller and controller is on. Verify solenoid supply air to gun is on. Verify air is present at gun and at correct pressure. Replace spring closure assembly if defective.
3. Gun not dispensing material, opening fully	Trimset valve blocked	Remove and clean the trimset valve. Refer to the appropriate Pro-Flo gun manual.
4. Gun not changing dispensing rate to control bead size	Cordset damaged	Check the continuity of cordset and replace if necessary. Refer to the appropriate Pro-Flo gun manual.
	Gun control or extension cable damaged	Check the continuity and replace cable if necessary. Refer to the appropriate Pro-Flo gun manual.
5. Gun not changing dispensing rate to control bead size, opening fully	Pressure transducer in controller malfunctioning	Check the pressure output voltage of the controller board. Contact your Nordson Corporation representative.
6. Gun dispensing early, before robot moves	Signals from robot controller timed improperly	Set proper timing sequence. Refer to *Setting Timing Sequences* in the *Installation* section.
	Gun On or Tool Speed delay too short	Increase parameter settings. Refer to the *Operation* section.
7. Gun dispensing after cycle, gun closed	Control air pressure low	Check supply air pressure and increase if necessary.
	Needle not seating	Purge the gun. Refer to the appropriate Pro-Flo gun manual.
	Stem and trimset valve seat worn	Replace trimset valve. Refer to the appropriate Pro-Flo gun manual.

2. Troubleshooting the Pro-Flo Controller (contd)

Problem	Possible Cause	Corrective Action
8. Dispensing delayed	Gun On signal from robot controller timed improperly	Set the proper timing sequence. Refer to *Setting Timing Sequences* in the *Installation* section.
	Gun On delay too long	Decrease the parameter setting. Refer to the *Operation* section.
	Stem binding (packing-type bonnet only)	Loosen packing nut. Refer to the appropriate Pro-Flo gun manual.
9. Bead deposition "wiggles"	Nozzle too high above work piece	Lower the nozzle. Refer to the *Robot Controller* manual.
	Material speed through nozzle too high	Decrease the bead size. Refer to *User Interface* in the *Operation* section.
	Nozzle not large enough	Install a larger nozzle. Contact your Nordson Corporation representative for part numbers.
10. Unexpected bead-size change	Nozzle partially blocked	Clean the nozzle. Refer to the appropriate Pro-Flo gun manual.
	Material exceeded shelf life	Use fresh material.
11. Material leaks from bonnet	Bonnet seals worn (lip seal-type only)	Replace the bonnet. Refer to the appropriate Pro-Flo gun manual.
	Bonnet screw loose (packing-type only)	Tighten the bonnet screw. Refer to the appropriate Pro-Flo gun manual.
	Bonnet packings worn (packing-type only)	Replace the bonnet. Refer to the appropriate Pro-Flo gun manual.

Section 6

Repair

Section 6
Repair

WARNING: Allow only qualified personnel to perform the following tasks. Follow the safety instructions in this document and all other related documentation.

1. Introduction

WARNING: Disconnect equipment from the line voltage. Failure to observe this warning may result in personal injury, death, or equipment damage.

2. Replacing the Controller

To replace the controller:

1. Turn off and lock out external electrical power to the controller.
2. Disconnect the cables and power leads.
3. Replace the controller with an identical unit.
4. Connect the cables and power leads.
5. Turn on electrical power to the controller.

3. Replacing Components

The Pro-Flo System is modular in design, with components that are easily removed and replaced. Refer to the *Parts* section for part numbers of necessary components.

Power Supply

Use this procedure to replace the power supply.

1. See Figure 6-1. Turn off and lock out external electrical power to the controller. Turn off the main rotary switch (5).

2. Open the enclosure door and disconnect and mark the cables from the power supply (3) and power monitor board (2).

3. Remove the three screws that hold the power supply support (4) to the enclosure. Remove the power supply support.

Power Supply *(contd)*

4. Remove the two screws securing the power supply to the power supply support.
5. Mount the new power supply to the power supply support.
6. Bolt the power supply to the enclosure.
7. Connect the cables to the power supply and power monitor board (2).
8. Adjust the power supply by following the instructions in the power supply manual.
9. Shut the enclosure door. Turn on the main rotary switch (5) and the electrical power to the system. If the controller does not operate properly, turn off the power, open the enclosure, and check the plug connections.

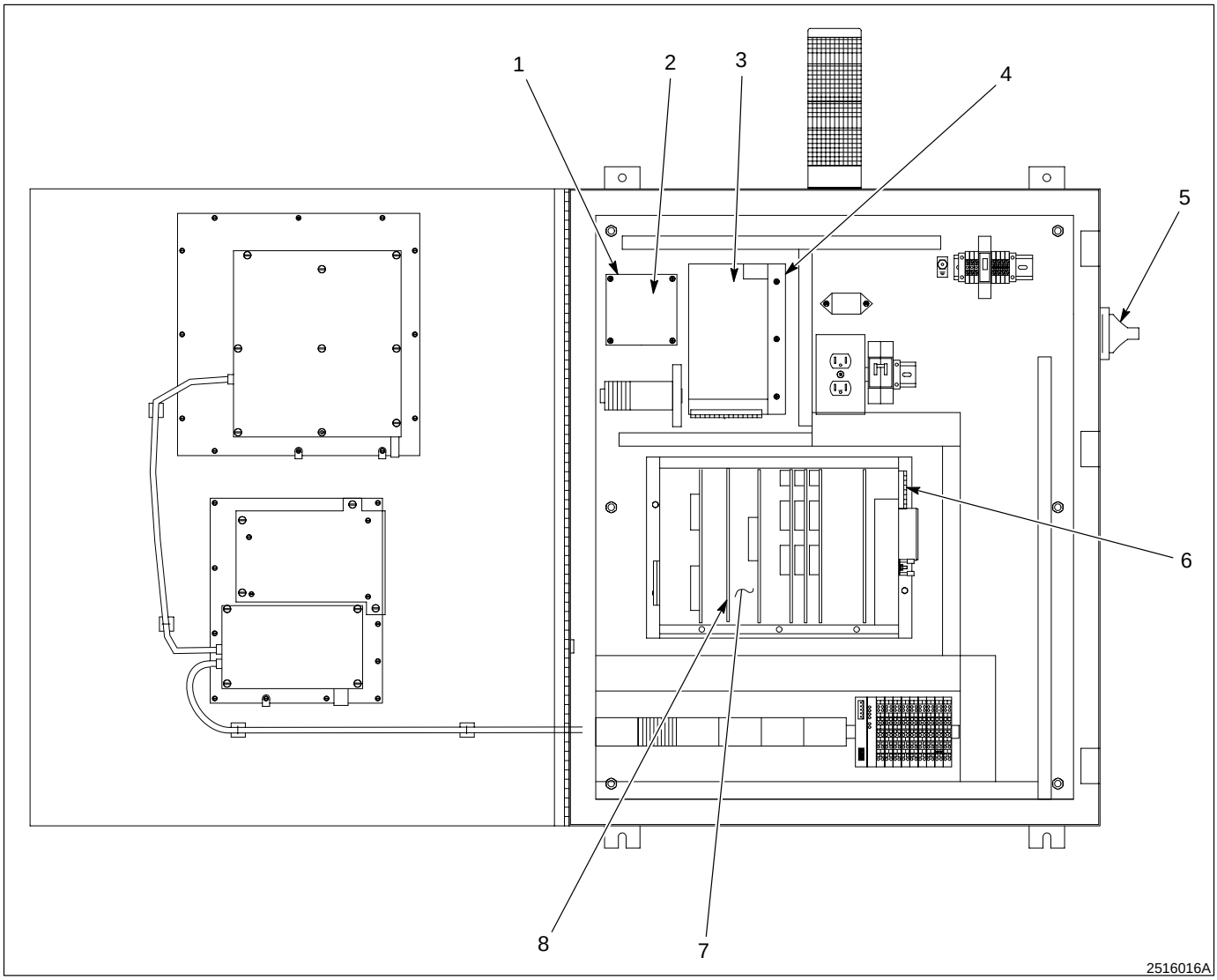


Fig. 6-1 Controller Assembly Components

1. Standoff
2. Power monitor board
3. Power supply
4. Power supply support
5. Main rotary switch
6. Card rack (installed)
7. Backplane
8. Circuit board

Power Monitor Circuit Board

Use this procedure to replace the power monitor circuit board.

1. See Figure 6-1. Turn off and lock out external electrical power to the controller. Turn off the main rotary switch (5).
2. Open the enclosure door. Remove the plastic cover and the cables from the power monitor board (2).
3. Note the position of the circuit board (8) and remove it by taking out the standoffs (1).
4. Note the position of the voltage switch on the circuit board. Set the switch on the new circuit board (8) to the same position.
5. Place the new power monitor board (2) in position.
6. Connect the cables.
7. Shut the enclosure door. Turn on the main rotary switch (5).
8. Turn on electrical power to the system.

Circuit Board in the Card Rack

Use this procedure to replace the circuit board in the card rack.

1. See Figure 6-1. Shut off and lock out external electrical power to the controller. Turn off the main rotary switch (5).
2. Open the enclosure door and remove the card rack (6).
3. See Figure 6-2. Mark and disconnect the cables from their connections (4). Mark and disconnect any other cable plugs from the circuit board (1).
4. Push the board ejector (2) to dislodge the circuit board (1). Slide the device from the slot in the card rack.
5. Note the position of the rotary switch (3). Set the switch on the new circuit board (1) to the same position.

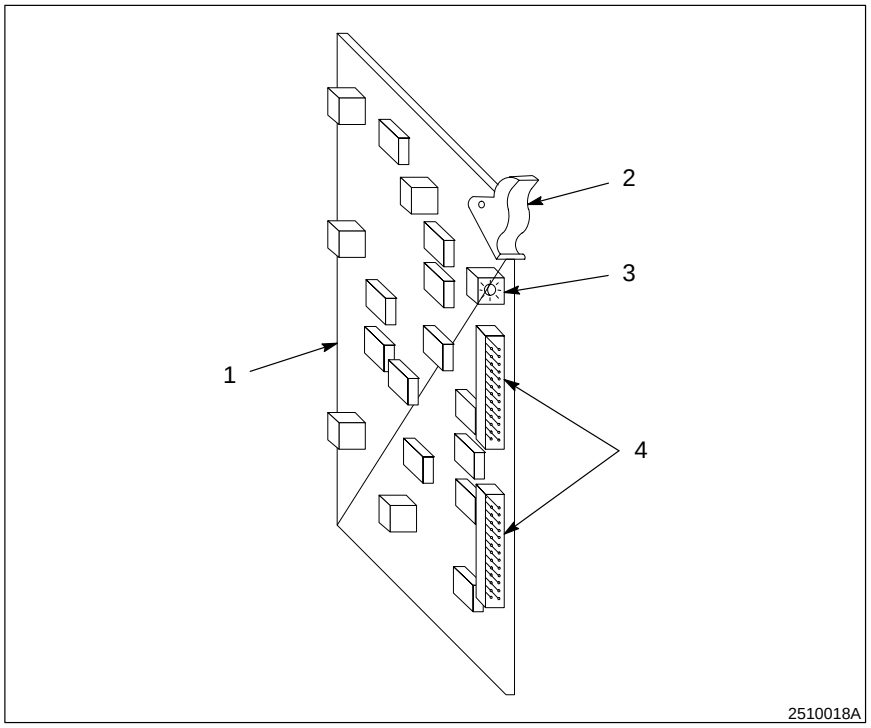


Fig. 6-2 Rotary Switch Setting (Board Address)

1. Circuit board
2. Board ejector
3. Rotary switch
4. Cable connections

NOTE: Circuit boards can be mounted in any position in the card rack. Addresses are determined by the board circuitry and rotary switch positions.

NOTE: When replacing a memory board, set the rotary switch to 14. When power is restored, make sure the following message is displayed: “SPC RAM 0 CONTROL INTERFACE INSTALLED.”

NOTE: For two I/O boards, set the rotary switch on the first to 0, and on the second to 1.

6. Slide the new circuit board (1) in the slot until it locks in place.

7. Connect the cables.

8. Shut the enclosure door. Turn on the main rotary switch. Turn on power to the controller.

NOTE: If the controller does not recognize the board and does not display a message during start up, turn off the controller and lock out power. Make sure the board is seated and the rotary switch is set properly.

Diagnostic Panel

Use this procedure to replace the diagnostic panel.

1. See Figure 6-1. Turn off and lock out external electrical power to the controller. Turn off the main rotary switch (5).
2. See Figure 6-3. Open the enclosure door and disconnect the cable from the diagnostic panel (1).
3. Remove the nine screws that hold the diagnostic panel to the enclosure door. Remove the diagnostic panel.
4. Bolt the new diagnostic panel to the enclosure door.
5. Connect the cable to the diagnostic panel.
6. See Figure 6-1. Shut the enclosure door. Turn on the main rotary switch (5) and the electrical power to the system. If the controller does not operate properly, turn off the power, open the enclosure, and check the plug connections.

VGA Display

See Figure 6-3. Use this procedure to replace the VGA Display.

1. See Figure 6-1. Turn off and lock out external electrical power to the controller. Turn off the main rotary switch (5).
2. Open the enclosure door.
3. See Figure 6-3. Remove the four screws that hold the VGA support plate to the enclosure door. Pull the support plate out slightly and disconnect the cable underneath. Remove the VGA support plate.
4. Remove the screws securing the VGA display (2) to the support plate.
5. Mount the new VGA display to the support plate.
6. Hold the support plate near its final position and connect the bottom cable. Bolt the support plate to the enclosure door.

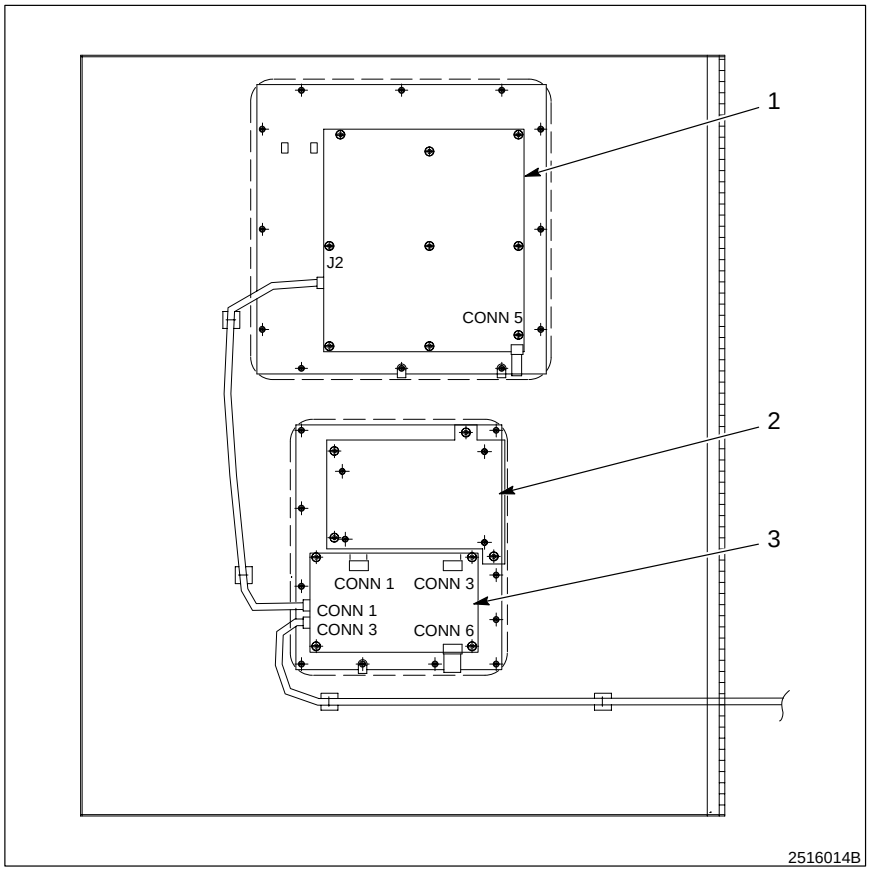


Fig. 6-3 Components Inside the Front Enclosure Door

1. Diagnostic Panel
2. VGA Display
3. Keypad

7. Shut the enclosure door. Turn on the main rotary switch and the electrical power to the system. If the controller does not operate properly, turn off the power, open the enclosure, and check the plug connections.

Keypad

Use this procedure to replace the keypad.

1. See Figure 6-1. Turn off and lock out external electrical power to the controller. Turn off the main rotary switch (5).
2. See Figure 6-3. Open the enclosure door and disconnect the two cables from the keypad (3).
3. Remove the six screws that hold the keypad to the enclosure door. Pull the keypad out slightly and disconnect the cable underneath. Remove the keypad.
4. Hold the new keypad near its final position and connect the bottom cable. Bolt the keypad to the enclosure door.
5. Connect the two cables to the keypad.
6. Shut the enclosure door. Turn on the main rotary switch and the electrical power to the system. If the controller does not operate properly, turn off the power, open the enclosure, and check the plug connections.

Cable Continuity

Cables should be checked periodically and replaced when worn or frayed. If a working system malfunctions, check that the cable connections are tight. Check the cables for continuity with an ohmmeter. Refer to the cable wiring tables given in the *Specifications* section.

Section 7

Parts

Section 7
Parts

1. Introduction

To order parts, call the Nordson Customer Service Center or your local Nordson representative. Use this five-column parts list, and the accompanying illustration, to describe and locate parts correctly.

Using the Illustrated Parts List

Numbers in the Item column correspond to numbers that identify parts in illustrations following each parts list. The code NS (not shown) indicates that a listed part is not illustrated. A dash (—) is used when the part number applies to all parts in the illustration.

The six-digit number in the Part column is the Nordson Corporation part number. A series of dashes in this column (- - - - - -) means the part cannot be ordered separately.

The Description column gives the part name, as well as its dimensions and other characteristics when appropriate. Indentions show the relationships between assemblies, subassemblies, and parts.

Item	Part	Description	Quantity	Note
—	000 000	Assembly	1	
1	000 000	• Subassembly	2	A
2	000 000	• • Part	1	

- If you order the assembly, items 1 and 2 will be included.
- If you order item 1, item 2 will be included.
- If you order item 2, you will receive item 2 only.

The number in the Quantity column is the quantity required per unit, assembly, or subassembly. The code AR (As Required) is used if the part number is a bulk item ordered in quantities or if the quantity per assembly depends on the product version or model.

Letters in the Note column refer to notes at the end of each parts list. Notes contain important information about usage and ordering. Special attention should be given to notes.

2. General Motors Pro-Flo Controller

See Figure 7-1.

Item	Part	Description	Quantity	Note
—	327 061	Controller, Pro-Flo Special II	1	
1	- - - - - -	• Enclosure	1	
2	281 714	• Switch, rotary, 3 pst	1	
3	281 739	• Circuit breaker, 6A, DPDT	1	
4	117 188	• Fan assembly	1	
5	107 499	• Back plane	1	
6	327 233	• Cable, assembly, 5 pin, male	1	
7	327 070	• Bus, coupler, DeviceNet	1	
8	327 071	• 2 Channel, 10 V, analog output module	1	
9	327 072	• 4 Channel, 24 V, discrete output module	1	
10	327 073	• 4 Channel, 24 V, discrete input module	1	
11	327 074	• Bus, terminal end	1	
12	105 987	• Board, circuit, I/O	3	
13	227 119	• Board, circuit, serial	1	
14	135 117	• Board, circuit, memory	1	
15	322 941	• Kit, CPU board	1	
16	325 287	• Kit, gun board	1	
17	230 672	• Interconnect cable diagnostic, panel to keypad, 5 ft	1	
18	160 4380	• PCA keypad panel, Pro-Flo	1	A, C
19	185 670	• Keyboard assembly, English	1	
20	160 4375	• Display, QVGA	1	B, C
21	282 960	• Interconnect cable diagnostic, keypad to console module, 2 ft	1	
22	327 462	• Diagnostic panel, English	1	
23	185 681	• PCA, diagnostic display	1	
24	109 302	• Board, circuit, power monitor	1	
25	233 612	• Board, circuit, power supply	1	
NS	160 4376	• Service kit, Pro-Flo display replacement		D

NOTE A: 1604380 PCA replaces obsolete part number 185657.
B: 1604375 display replaces obsolete part numbers 221699 and 1034019.
C: An obsolete keypad board (185657) will not work with a new display (1604375).
D: Service kit includes one 1604375 display and one 1604380 keypad panel.
NS: Not Shown

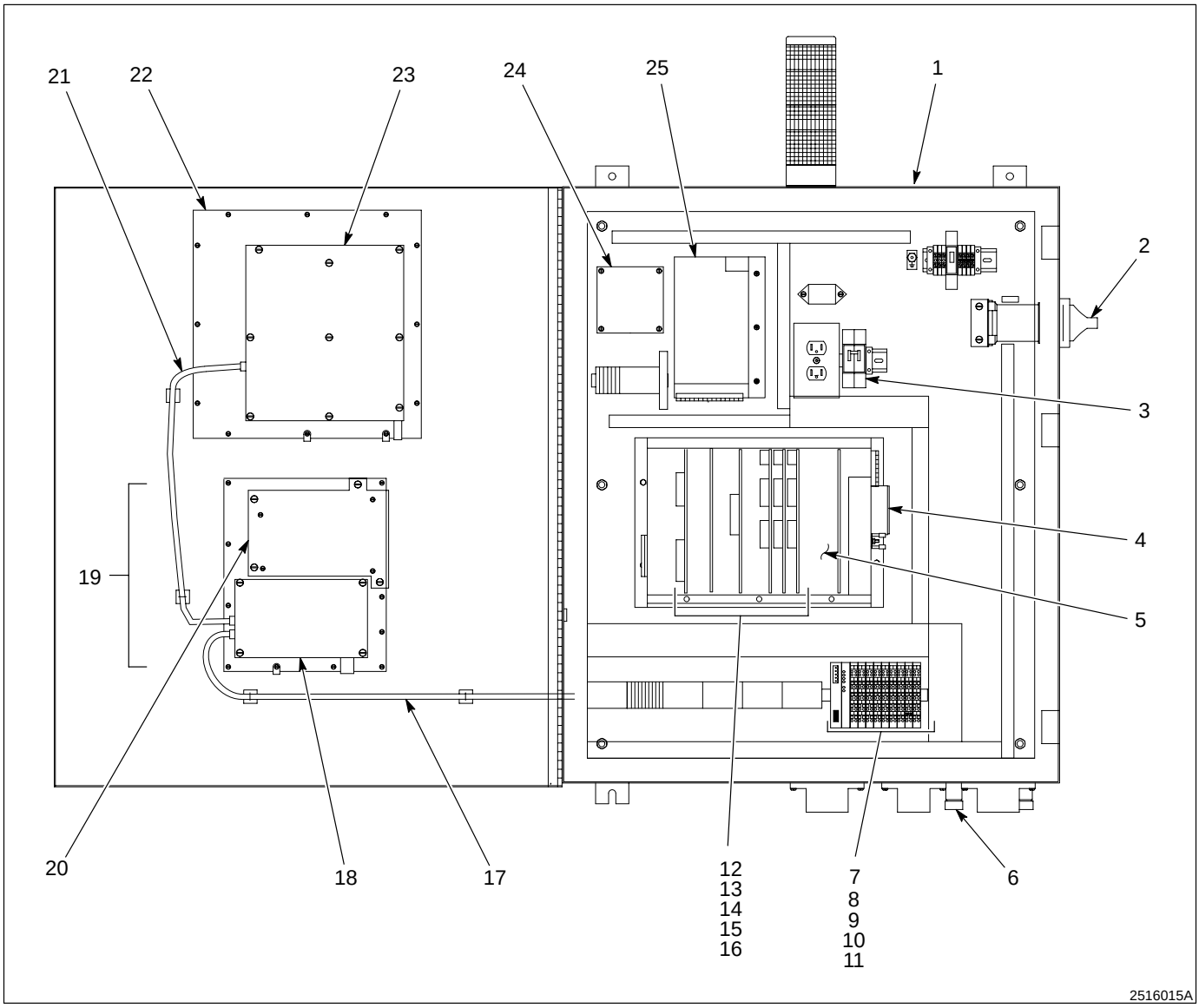


Fig. 7-1 Pro-Flo II Controller GMT 360

3. Accessories and Kits

These accessories may be purchased separately.

Part	Description	Note
281 132	Kit, proportioning valve (for air spray)	
154 376	Kit, material cut-off module	
144 259	Software program, DataLink, $3^1/_2$-in. disk	
144 260	Software program, DataLink, $5^1/_4$-in. disk	
155 450	Battery backup service kit	

4. Cable

Use this list to order replacement cables of the correct type and length.

Part	Description	Note
228 622	Cable, communication, 2 ft	
- - - - - -	Cable, robot, interface, 5 pin, DeviceNet	A
221 821	Cable, flowmeter assembly, 70 ft	
235 876	Cable, control, Pro-Flo gun, 70 ft	
235 872	Cable, control, Pro-Flo gun, sacrificial, 16 ft	
235 882	Sacrificial, flowmeter, cable, 16 ft	
235 841	Temperature, controller, interface, cable	
327 456	Cable, pump, interface, 70 ft	
327 442	Cable, temperature conditioner, 70 ft	
NOTE A: Customer supplied		

Section 8

Specifications

Section 8
Specifications

1. Electrical

The controller may be purchased for either 120 or 240 V line voltages. Each configuration requires 2A of current. Hard wire the controller into a dedicated power supply to provide safe operation and to reduce interference from electrical noise.

2. Cables

CAUTION: Make sure power is disconnected before removing cables and testing them.

The following charts will help you determine the continuity of Nordson Pro-Flo system cables.

Table 8-1 Gun Control Cable - Standard Interface

Controller End of Standard Cable (Pin Designator)	Function
U	Servo current (+)
T	Servo current (–)
S	Servo current (+)
R	Servo current (–)
P	Velocity/position transducer (–)
N	Velocity/position transducer (+)
M	Signal (+)
L	Signal (–)
K	Excitation (+5 V)
J	Excitation common (+5 V)
H	
G	
F	Shield/ground
U	Jumper (+)
T	Jumper (–)

Table 8-2 Flowmeter Manifold Cable - GMT 360 Interface

Controller End of Standard Cable (Pin Designator)	Wire Color	Function	J-Box End
2-1	Red	Excitation (+)	A
2-2	Black	Out (–)	B
2-3	White	Out (+)	C
2-4	Green	Excitation (–)	D
2-5	Shield	Drain	E
2-6	Blue	+15 V for FM	F
2-7	Brown	FM signal	H
2-8	Gray	Signal common	J
2-9	Shield	Drain	K
2-10	Purple	RTD (+)	L
2-11	Yellow	RTD (–)	M
2-12		MCO	N
2-13		Spring Closure Solenoid	I
2-14		24 Volt common	G
2-15		Not used	
2-16		Not used	

3. Robot Programming

Specification of the digital controller input and output signals and the fault codes generated are given to facilitate robot controller programming. Please refer to your robot controller manual for programming instructions.

Digital Controller

Table 8-3 Card 0 I/O List

Reference Signal	Board	I/O	Pin	Wire No.	Other Device	Final Terminal Location
Dispense Complete	0	Input	1	45	DeviceNet	02-A1
Style Strobe	0	Input	2	46	DeviceNet	03-A2
Depressurize Pumps	0	Input	3	47	DeviceNet	02-A3
Pressurize Pumps	0	Input	4	48	DeviceNet	03-A4
Temp. Cond. Power On	0	Input	5	49	Temp. Cond.	TC-4
FAULT ACK	0	Input	6	50	DeviceNet	04-A5
GUN ON	0	Input	7	51	DeviceNet	05-A6
PURGE	0	Input	8	52	DeviceNet	04-A7
DISPENSER READY	0	Output	1	53	DeviceNet	10-E1
Dispensing in Progress	0	Output	2	54	DeviceNet	11-E2
System is Depressurized	0	Output	3	55	DeviceNet	10-E3
Drum Empty	0	Output	4	56	DeviceNet	11-E4
MAJOR FAULT	0	Output	5	57	DeviceNet	12-E5
MINOR FAULT	0	Output	6	58	DeviceNet	13-E6
LIGHT TOWER-Major Fault	0	Output	7	59	LIGHT TOWER	
LIGHT TOWER-Minor Fault	0	Output	8	60	LIGHT TOWER	

Digital Controller (contd)

Table 8-4 Card 1 I/O List

Reference Signal	Board	I/O	Pin	Wire No.	Other Device	Final Terminal Location
Temp. Cond. System Fault	1	Input	1	62	Temp. Cond.	TC-6
Temp. Cond. Low Water Level	1	Input	2	63	Temp. Cond.	TC-7
PART ID (BIT 5) MSB	1	Input	3	64	DeviceNet	08-A13
PART ID (BIT 4)	1	Input	4	65	DeviceNet	07-A12
PART ID (BIT 3)	1	Input	5	66	DeviceNet	06-A11
PART ID (BIT 2)	1	Input	6	67	DeviceNet	07-A10
PART ID (BIT 1)	1	Input	7	68	DeviceNet	06-A9
PART ID (BIT 0) LSB	1	Input	8	69	DeviceNet	05-A8
VOLUME OK	1	Output	1	70	DeviceNet	12-E7
DISPENSER IN BACKUP	1	Output	2	71	DeviceNet	13-E8
Not Used		Output	3	72	Not Used	
USER ASSIGNED OUTPUT 1	1	Output	4	73	Connector 2	Pin 12
USER ASSIGNED OUTPUT 2	1	Output	5	74	Not Used	
USER ASSIGNED OUTPUT 3	1	Output	6	75	Not Used	
USER ASSIGNED OUTPUT 4	1	Output	7	76	Not Used	
Not Used	1	Output	8	77	Not Used	

Table 8-5 Card 2 I/O List

Reference Signal	Board	I/O	Pin	Wire No.	Other Device	Final Terminal Location
Pump Stand Ready	2	Input	1	78	Pump Stand	PS-4
Pump Runaway	2	Input	2	79	Pump Stand	PS-5
Filter Plugged	2	Input	3	80	Pump Stand	PS-6
Empty Drum 1	2	Input	4	81	Pump Stand	PS-7
Empty Drum 2	2	Input	5	82	Pump Stand	PS-8
Temp. Cond. Temp. Fault	2	Input	6	84	Temp. Cond.	TC-5
Not Used	2	Input	7	85	Not Used	
Not Used	2	Input	8	86	Not Used	
Depressurize Pumps	2	Output	1	87	Pump Stand	PS-9
Pressurize Pumps	2	Output	2	88	Pump Stand	PS-10
Not Used	2	Output	3		Not Used	
Not Used	2	Output	4		Not Used	
Not Used	2	Output	5		Not Used	
Not Used	2	Output	6		Not Used	
Not Used	2	Output	7		Not Used	
Not Used	2	Output	8		Not Used	
Analog Signal — Gun Board				22	DeviceNet	14-AO
Analog Signal — Gun Board				23	DeviceNet	14-(–)

Statistical Process Data Control (SPC) Data

Digital controllers equipped with an optional serial port interface may transfer SPC data logged by the controller to a personal computer. A computer running the Nordson DataLink program, which is sold separately, can receive data.

The SPC data is presented in ASCII format, as comma-delimited text.

Table 8-6 Format of SPC Data

Column	Parameter	Units[a]
1	Date	—
2	Time	—
3	Part ID	—
4	Bead size	—
5	Volume set point	cc, oz
6	Current volume	cc, oz
7	Material temperature	_F or _C
8	Upstream pressure	psi or bar
9	SPC fault code I[b]	—
10	System status	—
11	SPC fault code II[c]	—

[a]Units may be changed using the Nordson Configurator program.

[b]This SPC code contains the primary fault, which is also reported on the Pro-Flo controller help screens.

[c]This SPC code contains all faults generated: both primary and secondary.

Decoding SPC Error Listings

The SPC error code listing of errors that occurred during the running of a part. Follow these steps to decode an SPC error listing:

1. Subtract the largest number from the code column that yields a remainder greater than or equal to zero. This is the value of the first decoded error code.

2. If the remainder is greater than zero, subtract the largest number from the code column that yields a remainder greater than or equal to zero. This value is the second decoded error code.

3. Continue subtracting the largest possible value until a remainder of zero is obtained.

EXAMPLE: An error code of 1060 is listed. The largest code that can be subtracted is 1024. The remainder is 36. The largest code that can be subtracted from the remainder is 32. Subtracting 32 from 36 yields 4. The largest code that can be subtracted from 4 is 4. The remainder is 0 and decoding is complete. The following errors were detected:

- 1024 — High dispensed volume
- 32 — Low nozzle pressure, sensor failed
- 4 — Gun full open > set time

Table 8-7 SPC Error Codes

Code	Description
1	High dispensed volume
2	Low dispensed volume
4	High material supply pressure
8	Low material supply pressure
16	No material supply pressure
32	Nozzle clog or down stream blockage
64	Gun cable failure
128	Flowmeter/booster pump failure
256	Nozzle pressure transducer failure
512	Flowmeter cable failure
1024	Upstream pressure transducer failed
2048	Upstream pressure transducer cable failure
4096	Robot signals out of sequence
8192	Gun failure
16384	Bead defect detected

Decoding SPC Error Listings

(contd)

Table 8-8 SPC System Status Codes

Code	Description
1	In Back-up
2	Deferred Back-up
4	Material Calibration has been run
8	New pressure transducer offsets have been measured
16	“a” or “n” value has been changed through the keypad
32	The “a” value changed due to a purge
64	Cold Start Timer timed out
128	New Configuration file or defaults have been loaded
256	SPC data has been down loaded
512	Blank
1024	Blank
2048	Blank
4096	Blank
8192	Blank
16384	Blank
32768	Blank

4. Connectors

Connector 1 to Pro-Flo Gun		
Pin No.	**Wire No.**	**Function**
A	—	—
B	—	—
C	—	—
D	—	—
E	—	—
F	GND	Shield
G	—	—
H	—	—
J	34	Exitation (–)
K	31	+ 5 volt exitation
L	32	Signal (–)
M	33	Signal (+)
N	38	Velocity transducer (–)
P	37	Velocity transducer (+)
R	—	—
S	—	—
T	39	Servo drive return
U	40	Servo drive (+)

Connector 2 to J-Box (for flowmeter, etc.)		
Pin No.	**Wire No.**	**Function**
1	27	+ 5 volt exitation
2	28	Signal (–)
3	29	Signal (+)
4	30	Exitation (–)
5	GND	Shield
6	19	+15 volts for flow meter
7	20	Flow meter signal
8	21	Common
9	GND	Shield
10	26	RTD (+)
11	25	RTD (–)
12	73	User assigned output #1
13	13	+ 24 volts for spring closure
14	16	24 volt common
15	—	Spare
16	—	Spare
GND	GND	Ground

Connector TC for Temperature Conditioner		
Pin No.	**Wire No.**	**Function**
1	13	+ 24 volts
2	16	24 volt common
3	GND	Ground
4	49	Temp. cond. power on
5	84	Temp. cond. temp fault
6	62	Temp. cond. system fault
7	63	Temp. cond. low water level
8	—	—
9	—	—
10	—	—
GND	GND	Ground

Connector PS for Pump Stand		
Pin No.	**Wire No.**	**Function**
1	13	+ 24 volts
2	16	24 volt common
3	GND	Ground
4	78	Pump stand ready
5	79	Pump runaway
6	80	Filter clogged
7	81	Empty drum #1
8	82	Empty drum #2
9	87	Depressurize pumps
10	88	Pressurize pumps
11	—	—
12	—	—
13	—	—
14	5L1	120 Vac
15	1L2	Neutral (120 Vac)
16	—	Ground
GND	GND	Ground

DeviceNet		
Pin No.	**Wire No.**	**Function**
1	96 (R)	Supply voltage
2	98 (O)	Signal high
3	95 (W)	Shield
4	99 (BK)	Signal low
5	97 (G)	Supply common

5. Circuit Board Layouts

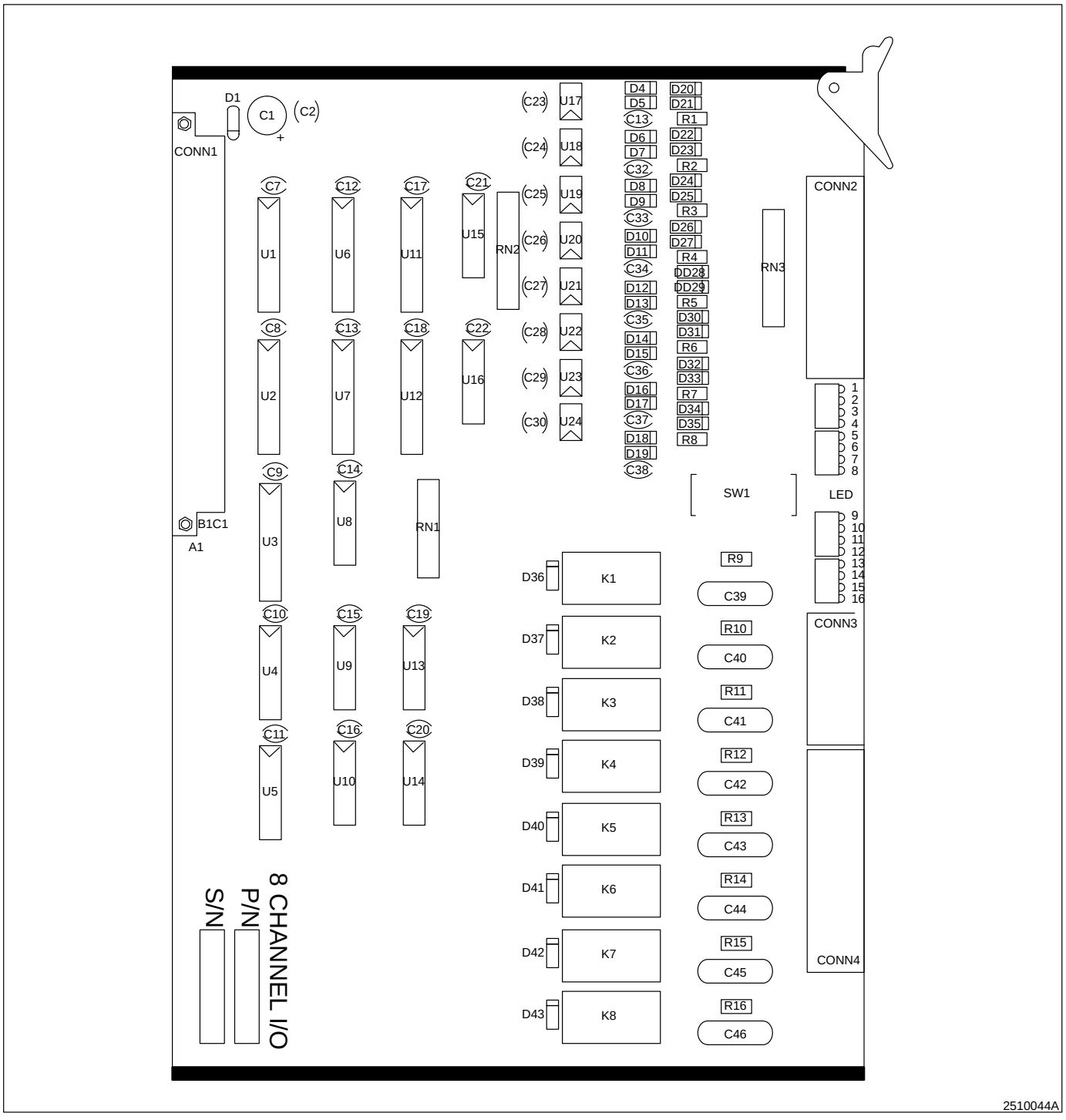


Fig. 8-1 Eight-Channel I/O Board Layout

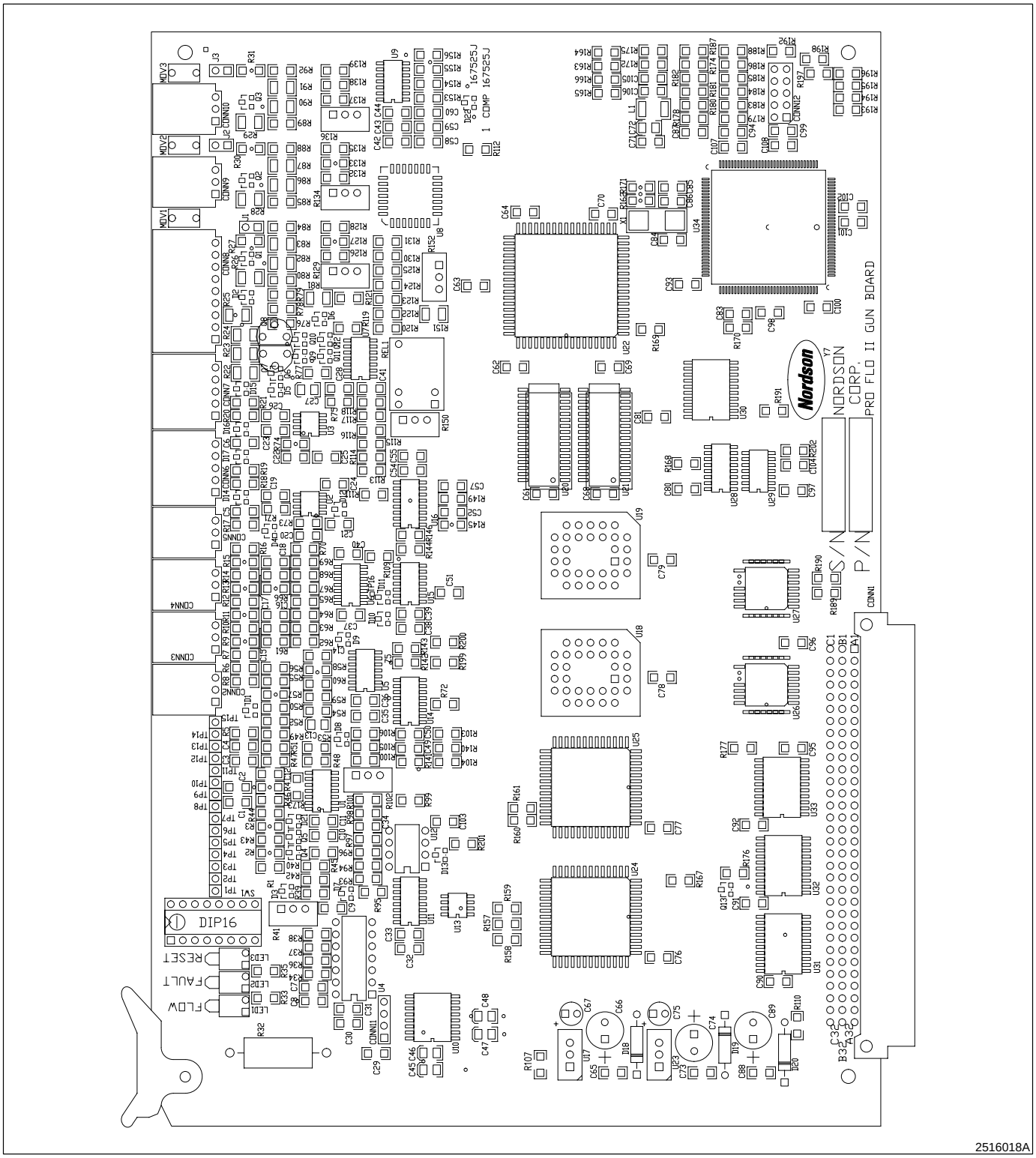


Fig. 8-2 Gun Board Layout

5. Circuit Board Layouts
(contd)

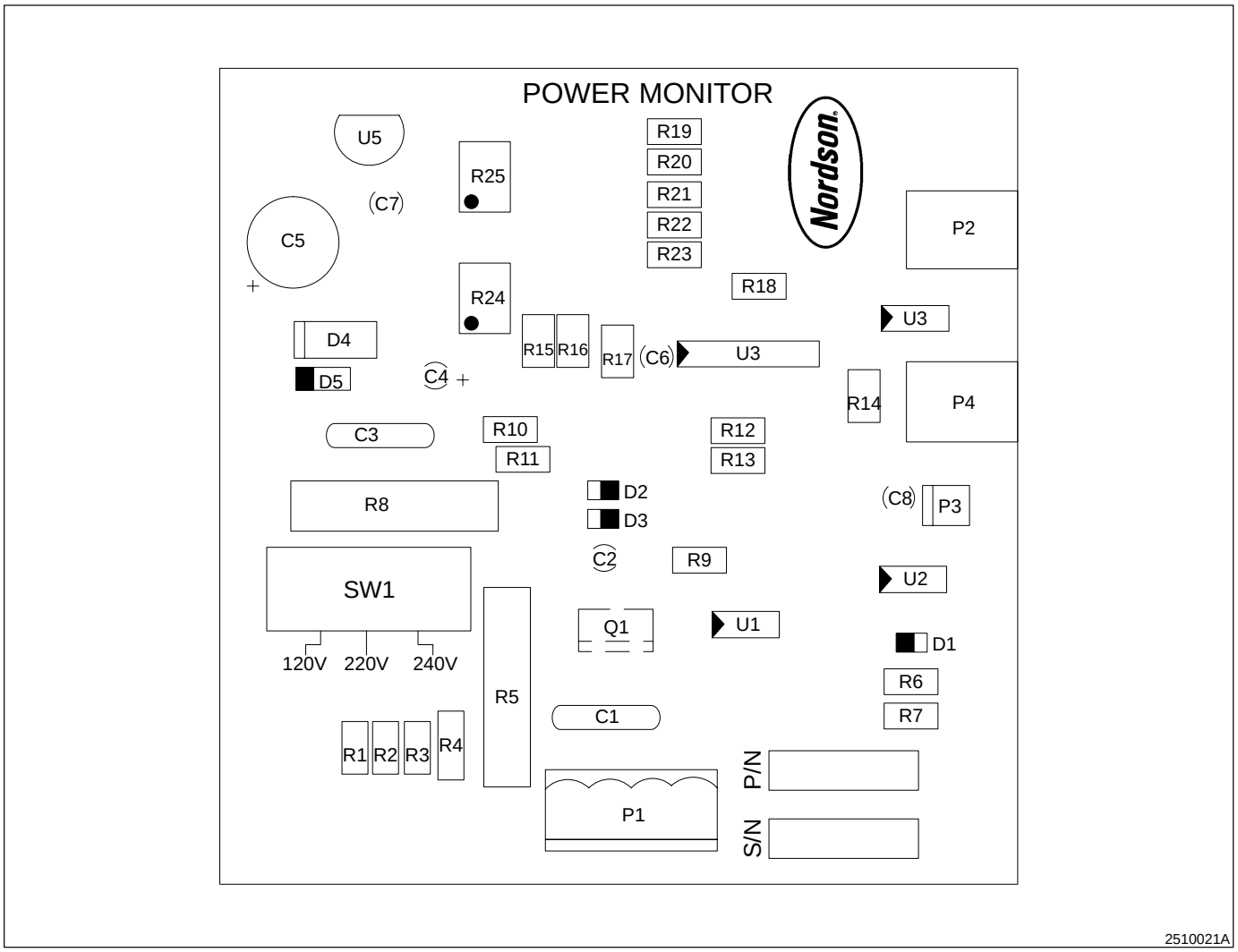


Fig. 8-3 Power Monitor Board Layout

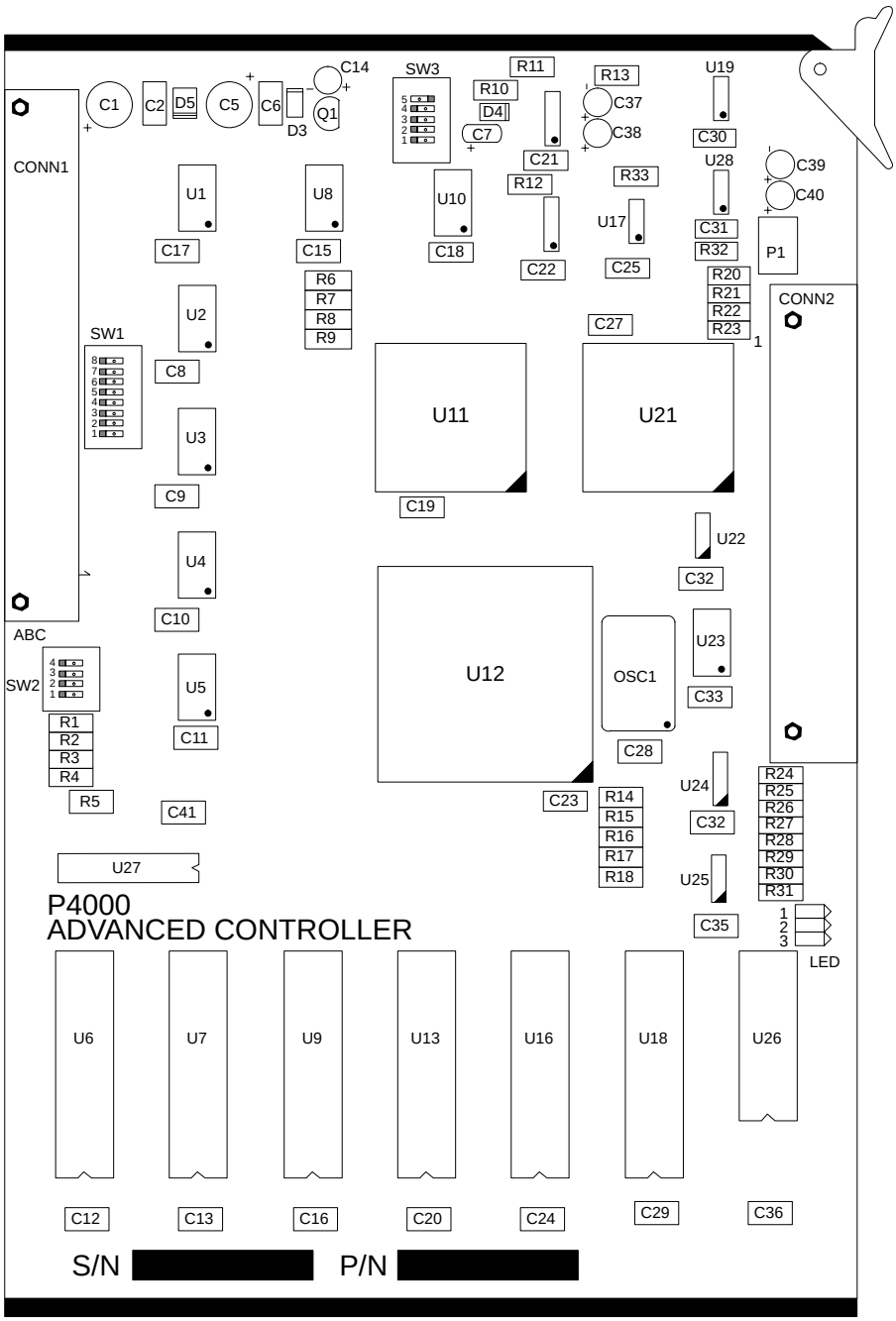


Fig. 8-4 Advanced Controller Board Layout

5. Circuit Board Layouts
(contd)

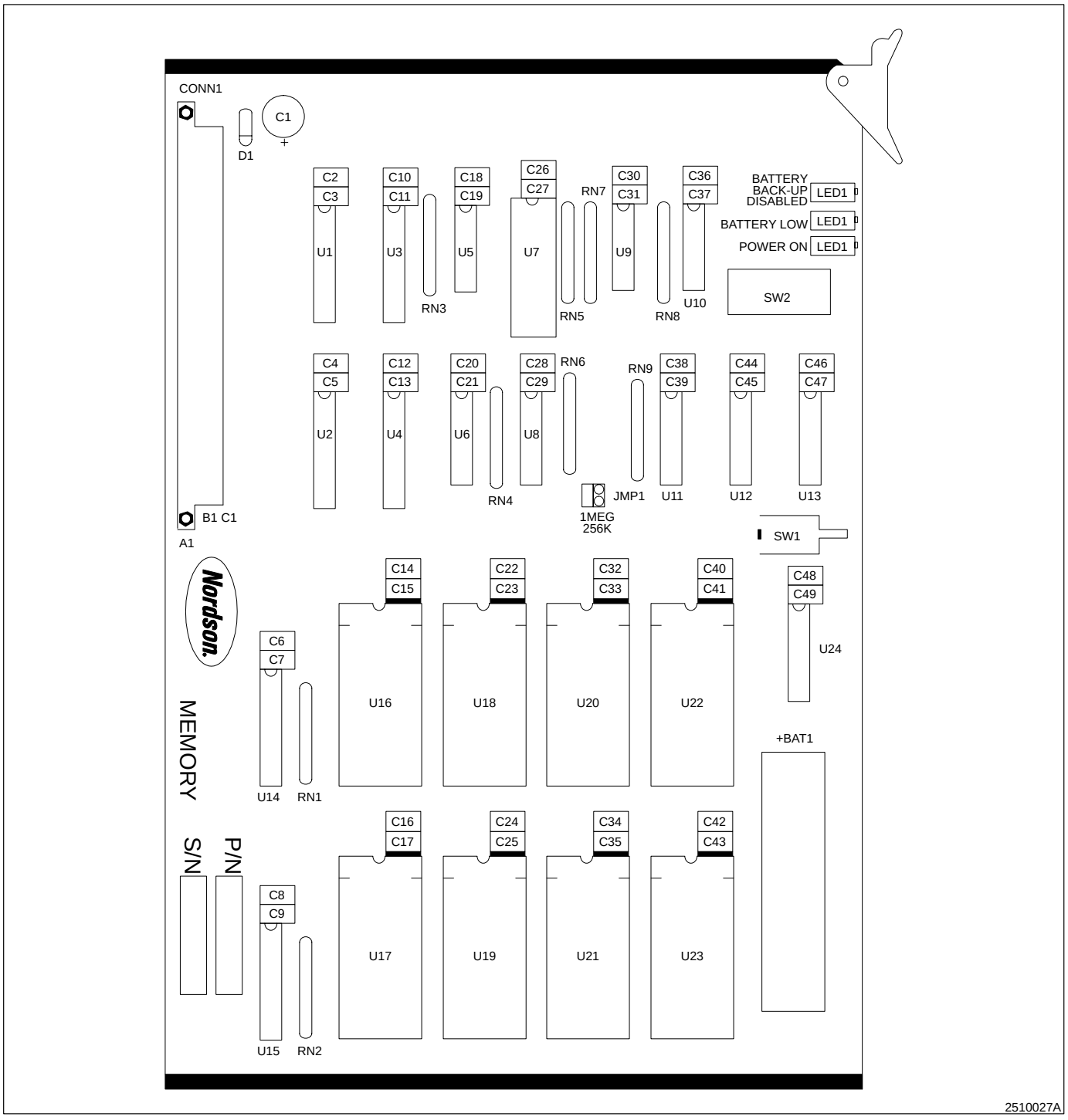
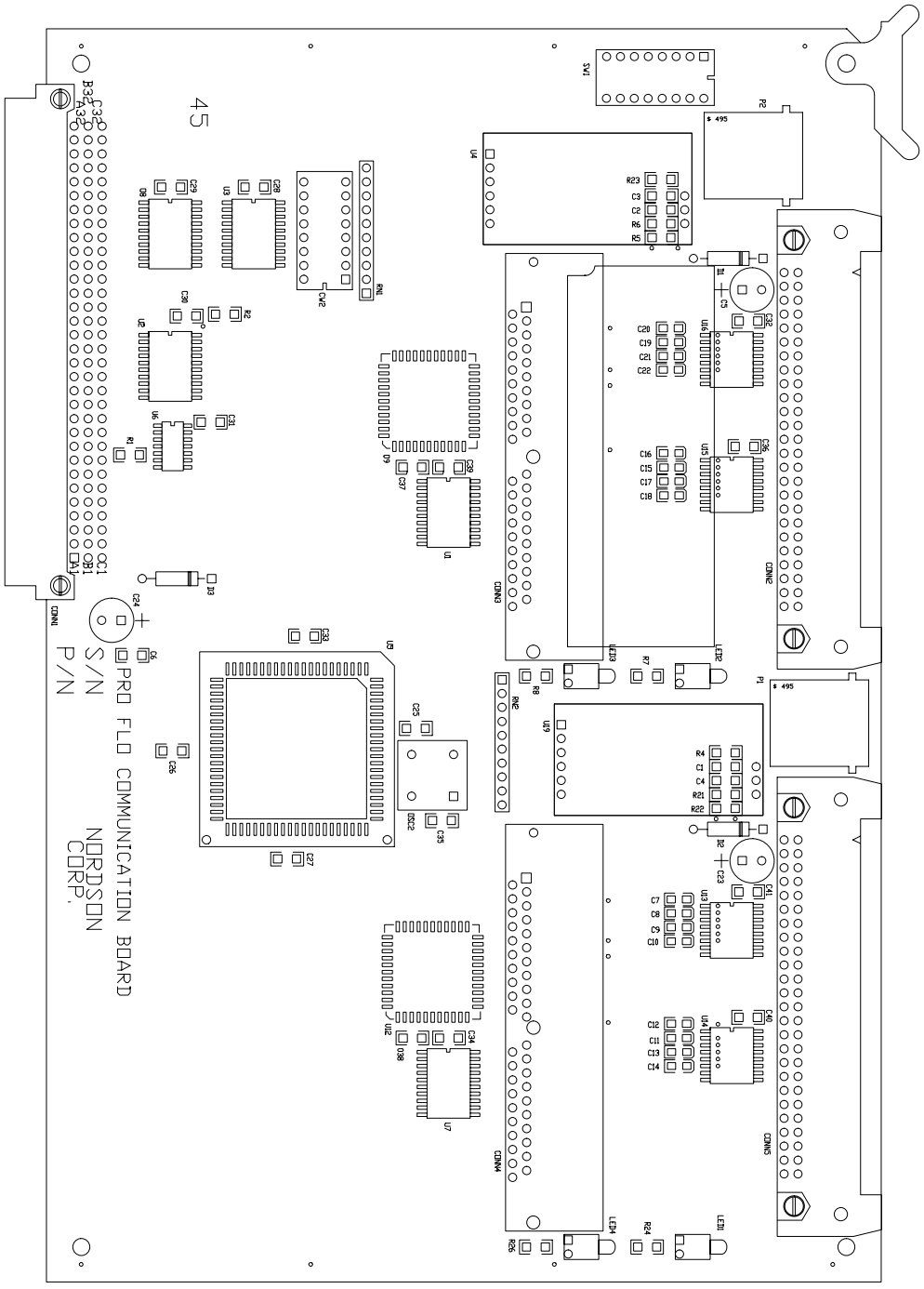


Fig. 8-5 Memory Board Layout (1 meg)



2510030B

Fig. 8-6 Serial Interface Board Layout

5. Circuit Board Layouts
(contd)

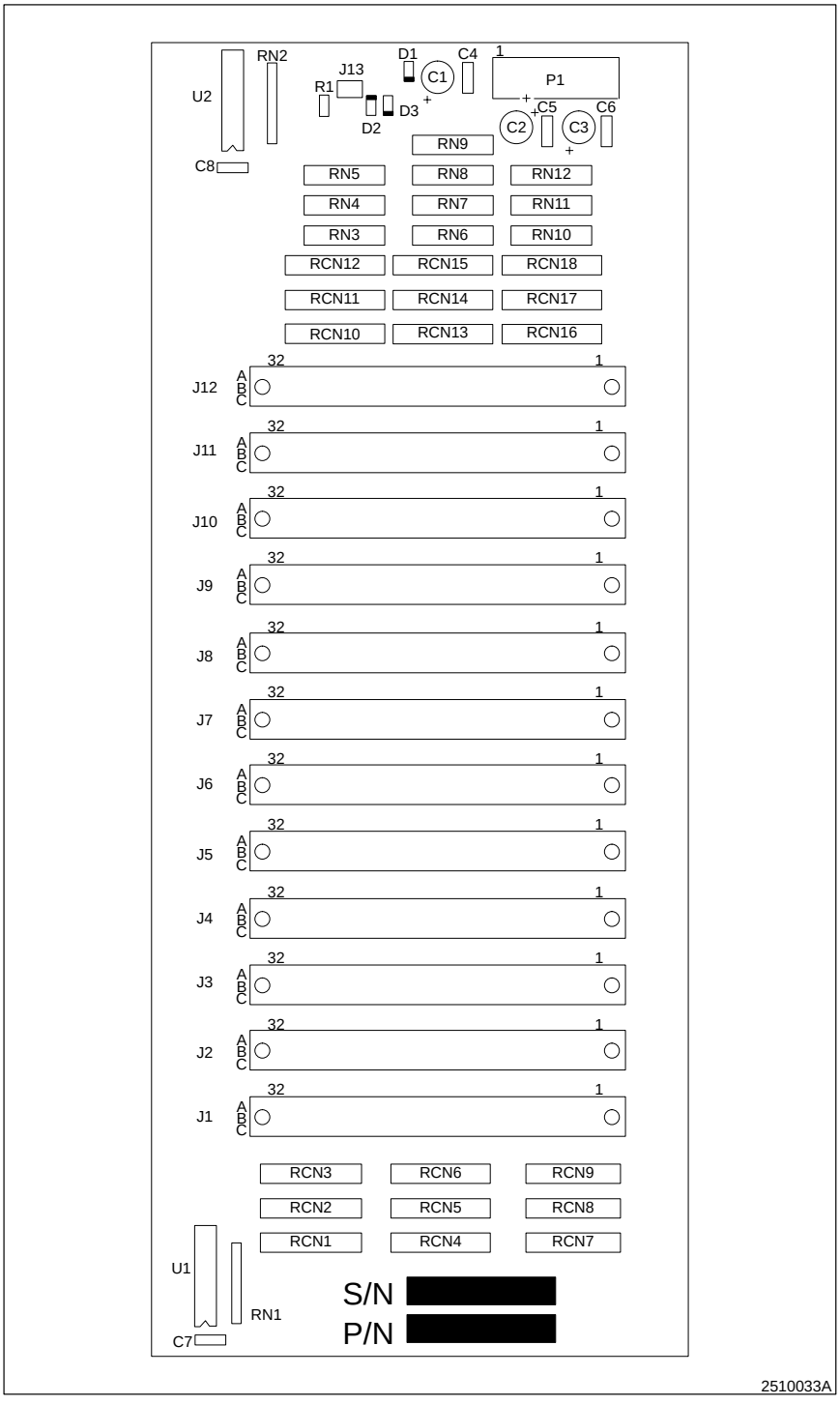


Fig. 8-7 Backplane Board Layout

6. Controller Wiring Diagrams

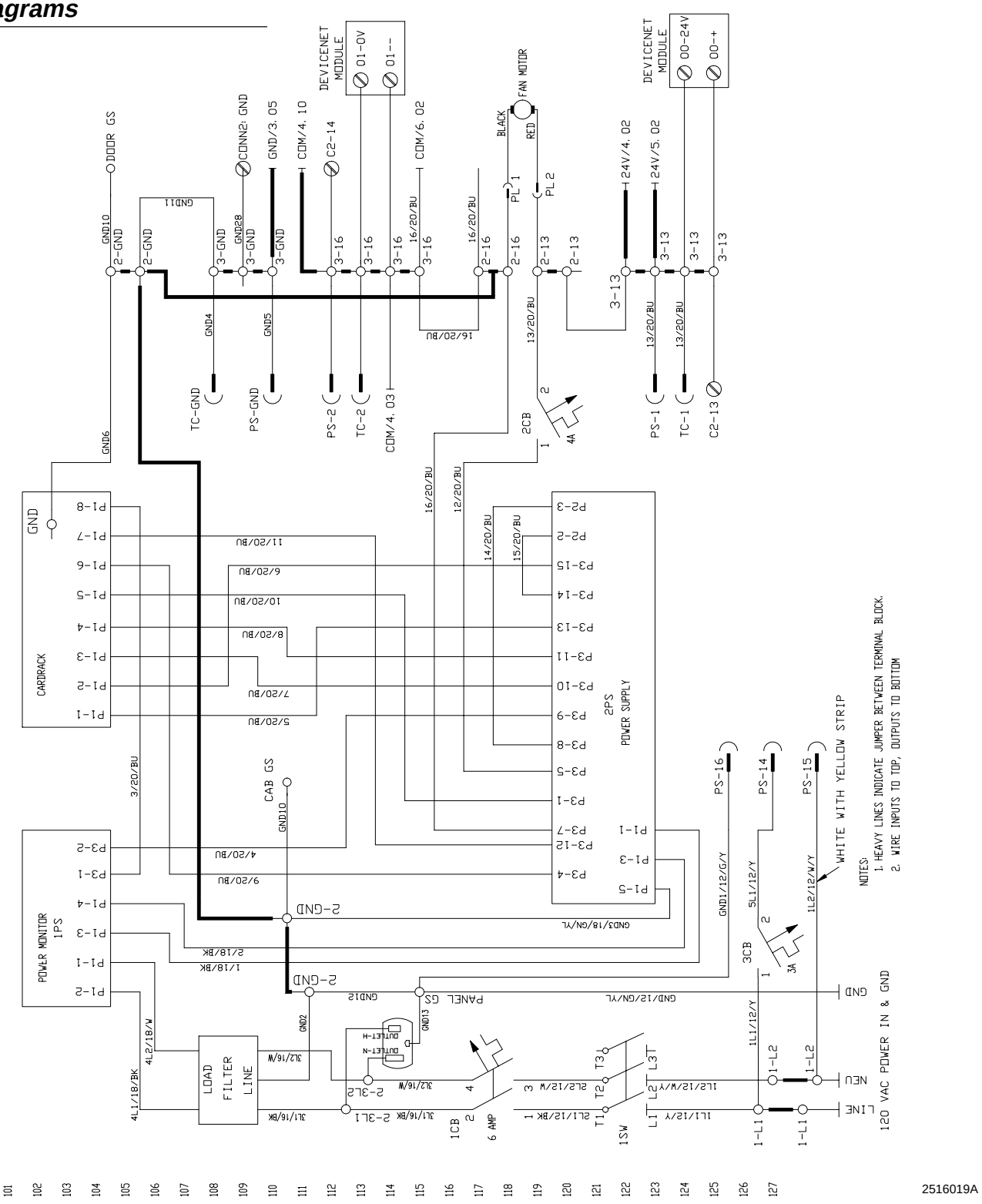
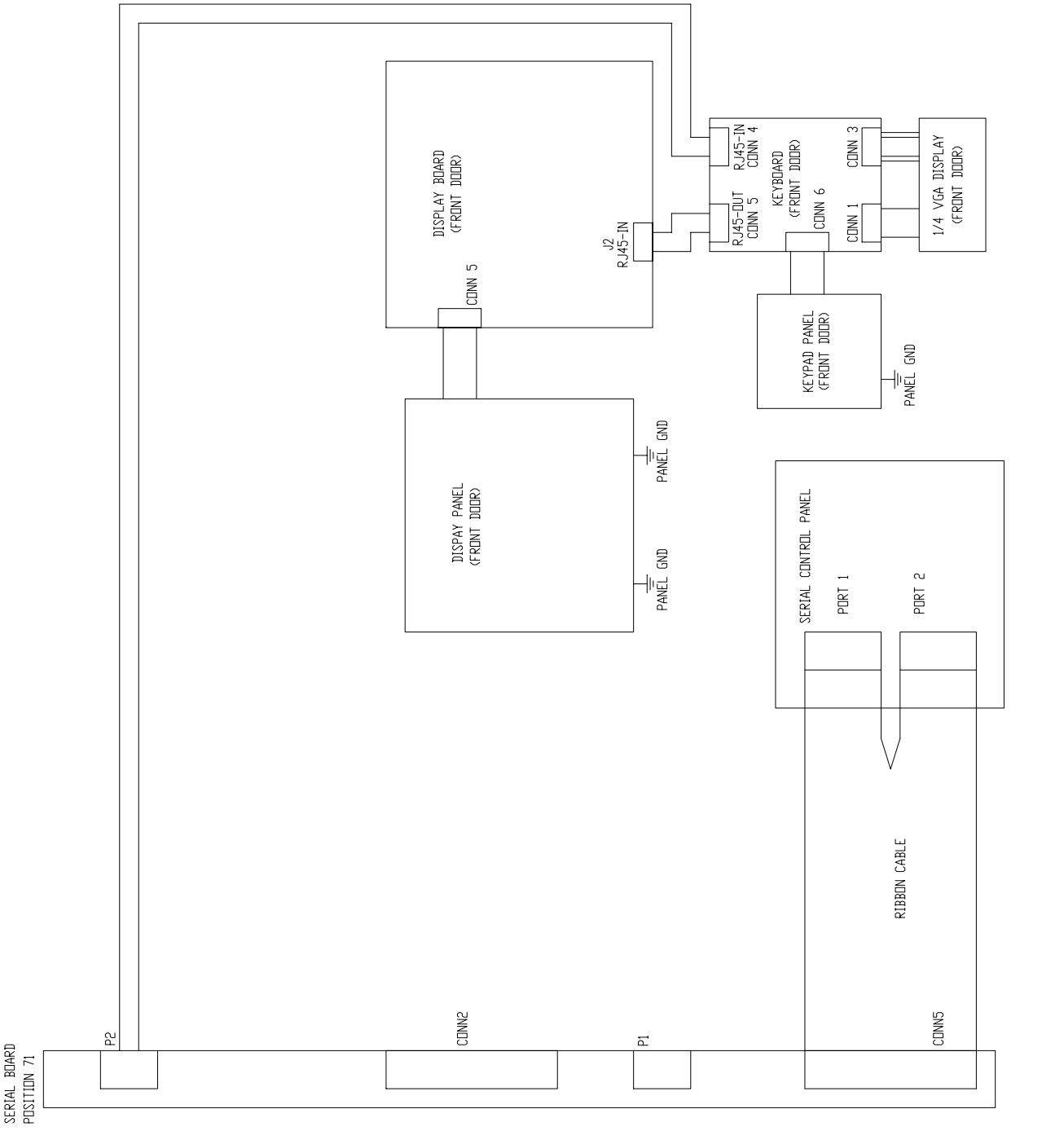


Fig. 8-8 Controller Wiring Diagram (1 of 6)



2516001A

Fig. 8-9 Controller Wiring Diagram (2 of 6)

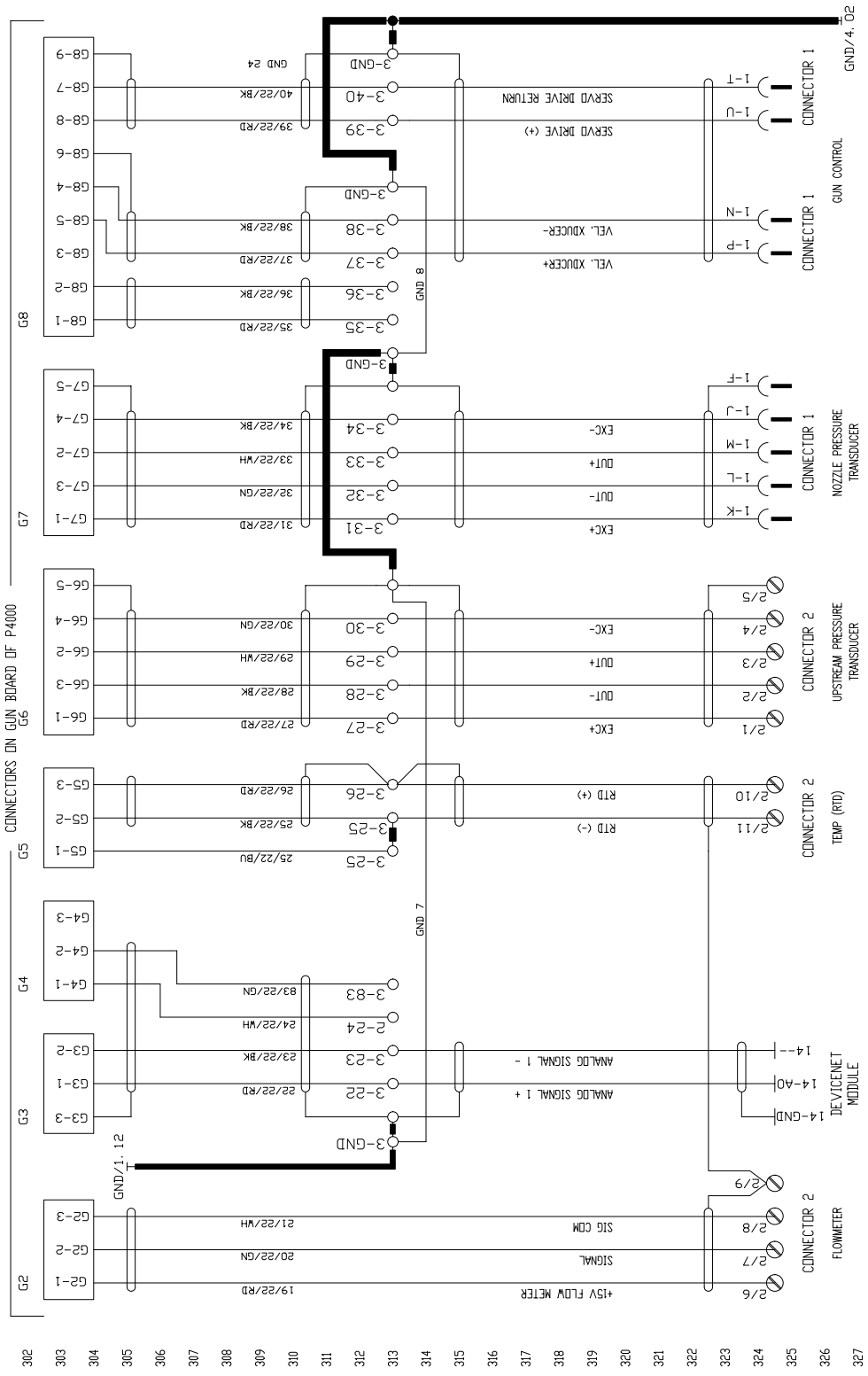


Fig. 8-10 Controller Wiring Diagram (3 of 6)

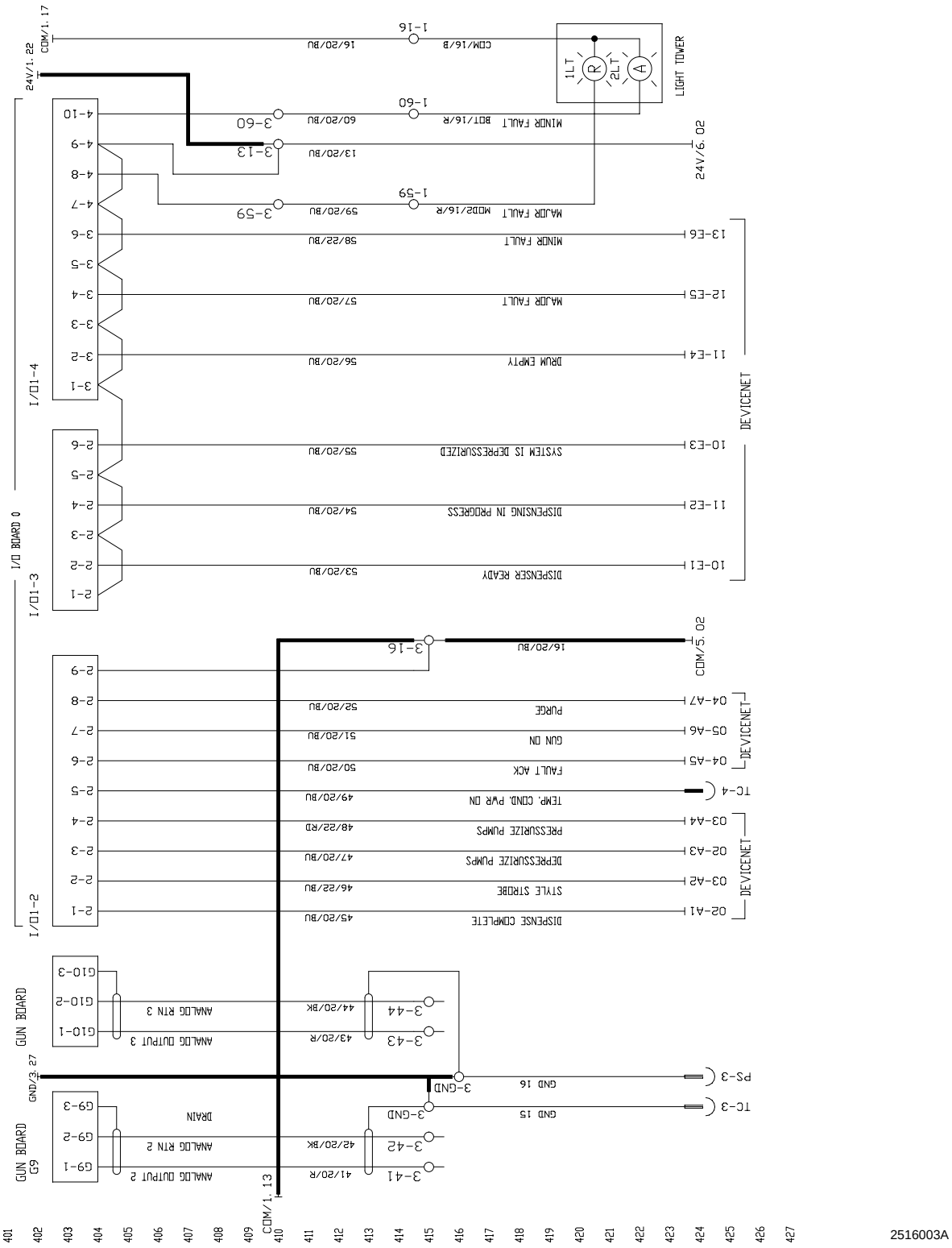


Fig. 8-11 Controller Wiring Diagram (4 of 6)

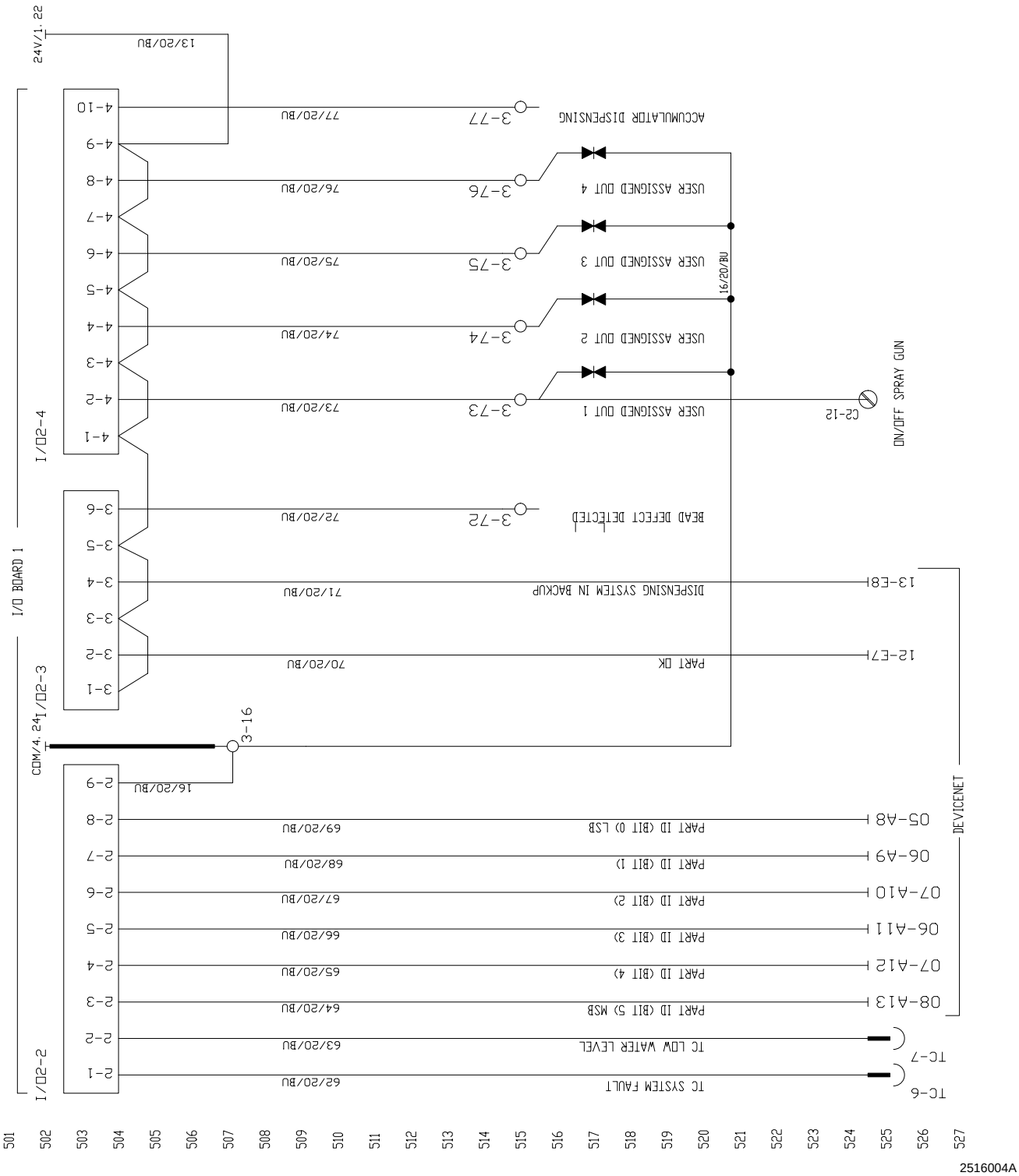


Fig. 8-12 Controller Wiring Diagram (5 of 6)

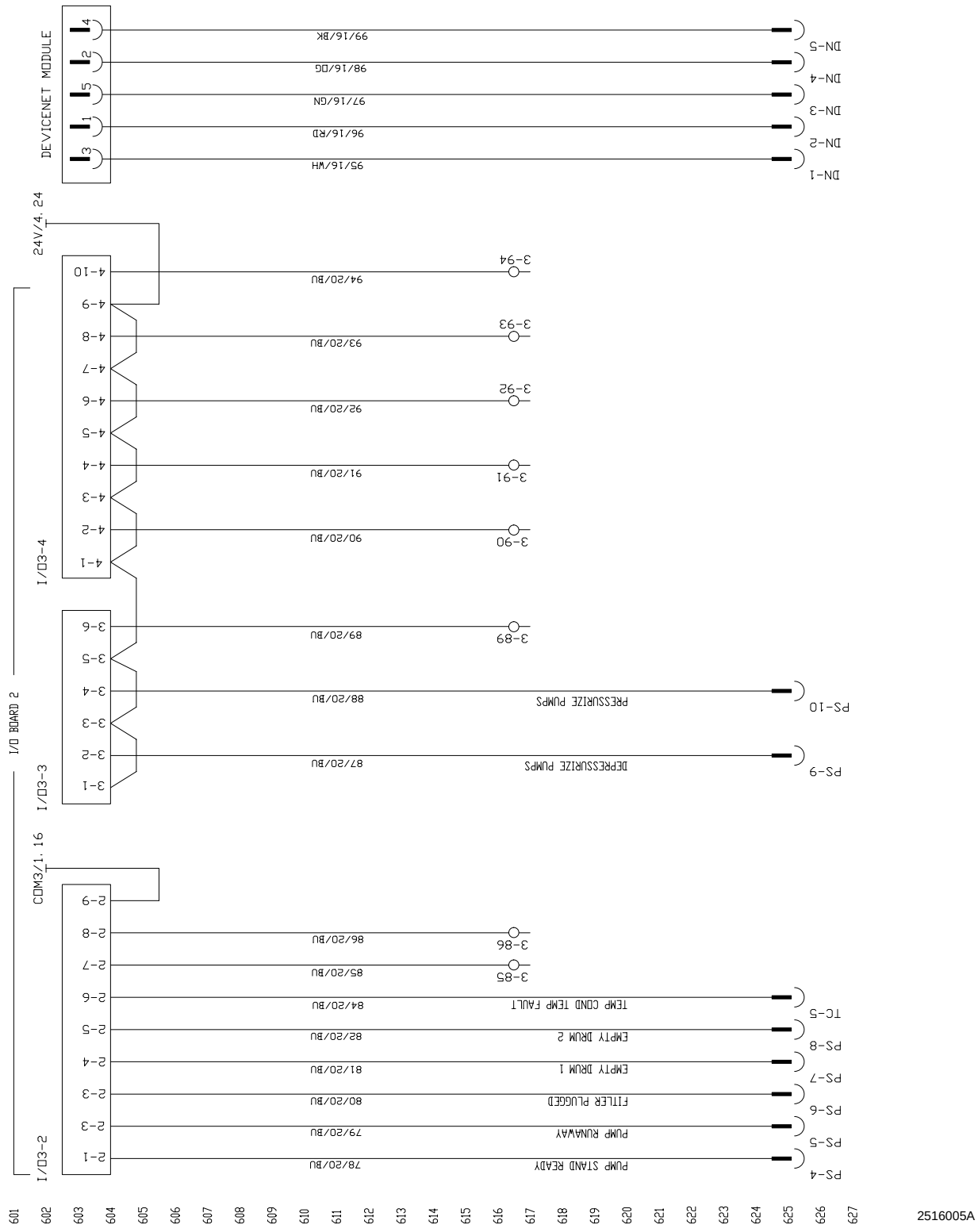


Fig. 8-13 Controller Wiring Diagram (6 of 6)