Dual Pro-Meter S-Series
FANUC Interface PCI Controller

Product Manual 1108206A
Issued 4/11

For parts and technical support, call the
Finishing Customer Support Center at (800) 433-9319.

This document is subject to change without notice.

NORSDON CORPORATION • AMHERST, OHIO • USA
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Trademarks
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All other trademarks are the property of their respective owners.
Safety

Read and follow these safety instructions. Task- and equipment-specific warnings, cautions, and instructions are included in equipment documentation where appropriate.

Make sure all equipment documentation, including these instructions, is accessible to persons operating or servicing equipment.

Qualified Personnel

Equipment owners are responsible for making sure that Nordson equipment is installed, operated, and serviced by qualified personnel. Qualified personnel are those employees or contractors who are trained to safely perform their assigned tasks. They are familiar with all relevant safety rules and regulations and are physically capable of performing their assigned tasks.

Intended Use

Use of Nordson equipment in ways other than those described in the documentation supplied with the equipment may result in injury to persons or damage to property.

Some examples of unintended use of equipment include:
- using incompatible materials
- making unauthorized modifications
- removing or bypassing safety guards or interlocks
- using incompatible or damaged parts
- using unapproved auxiliary equipment
- operating equipment in excess of maximum ratings

Regulations and Approvals

Make sure all equipment is rated and approved for the environment in which it is used. Any approvals obtained for Nordson equipment will be voided if instructions for installation, operation, and service are not followed.

Personal Safety

To prevent injury follow these instructions.

- Do not operate or service equipment unless you are qualified.
- Do not operate equipment unless safety guards, doors, or covers are intact and automatic interlocks are operating properly. Do not bypass or disarm any safety devices.
- Keep clear of moving equipment. Before adjusting or servicing moving equipment, shut off the power supply and wait until the equipment comes to a complete stop. Lock out power and secure the equipment to prevent unexpected movement.
- Relieve (bleed off) hydraulic and pneumatic pressure before adjusting or servicing pressurized systems or components. Disconnect, lock out, and tag switches before servicing electrical equipment.
- While operating manual spray guns, make sure you are grounded. Wear electrically conductive gloves or a grounding strap connected to the gun handle or other true earth ground. Do not wear or carry metallic objects such as jewelry or tools.
- If you receive even a slight electrical shock, shut down all electrical or electrostatic equipment immediately. Do not restart the equipment until the problem has been identified and corrected.
- Obtain and read Material Safety Data Sheets (MSDS) for all materials used. Follow the manufacturer's instructions for safe handling and use of materials, and use recommended personal protection devices.
- Make sure the spray area is adequately ventilated.
- To prevent injury, be aware of less-obvious dangers in the workplace that often cannot be completely eliminated, such as hot surfaces, sharp edges, energized electrical circuits, and moving parts that cannot be enclosed or otherwise guarded for practical reasons.
High-Pressure Fluids

High-pressure fluids, unless they are safely contained, are extremely hazardous. Always relieve fluid pressure before adjusting or servicing high pressure equipment. A jet of high-pressure fluid can cut like a knife and cause serious bodily injury, amputation, or death. Fluids penetrating the skin can also cause toxic poisoning.

If you suffer a fluid injection injury, seek medical care immediately. If possible, provide a copy of the MSDS for the injected fluid to the health care provider. The National Spray Equipment Manufacturers Association has created a wallet card that you should carry when you are operating high-pressure spray equipment. These cards are supplied with your equipment. The following is the text of this card:

**WARNING:** Any injury caused by high pressure liquid can be serious. If you are injured or even suspect an injury:

- Go to an emergency room immediately.
- Tell the doctor that you suspect an injection injury.
- Show him this card
- Tell him what kind of material you were spraying

**MEDICAL ALERT—WOUNDS:**

**NOTE TO PHYSICIAN**

Injection in the skin is a serious traumatic injury. It is important to treat the injury surgically as soon as possible. Do not delay treatment to research toxicity. Toxicity is a concern with some exotic coatings injected directly into the bloodstream.

Consultation with a plastic surgeon or a reconstructive hand surgeon may be advisable.

The seriousness of the wound depends on where the injury is on the body, whether the substance hit something on its way in and deflected causing more damage, and many other variables including skin microflora residing in the paint or gun which are blasted into the wound. If the injected paint contains acrylic latex and titanium dioxide that damage the tissue’s resistance to infection, bacterial growth will flourish. The treatment that doctors recommend for an injection injury to the hand includes immediate decompression of the closed vascular compartments of the hand to release the underlying tissue distended by the injected paint, judicious wound debridement, and immediate antibiotic treatment.

**Fire Safety**

To avoid a fire or explosion, follow these instructions.

- Ground all conductive equipment. Use only grounded air and fluid hoses. Check equipment and workpiece grounding devices regularly. Resistance to ground must not exceed one megohm.
- Shut down all equipment immediately if you notice static sparking or arcing. Do not restart the equipment until the cause has been identified and corrected.
- Do not smoke, weld, grind, or use open flames where flammable materials are being used or stored.
- Do not heat materials to temperatures above those recommended by the manufacturer. Make sure heat monitoring and limiting devices are working properly.
- Provide adequate ventilation to prevent dangerous concentrations of volatile particles or vapors. Refer to local codes or your material MSDS for guidance.
- Do not disconnect live electrical circuits when working with flammable materials. Shut off power at a disconnect switch first to prevent sparking.
- Know where emergency stop buttons, shutoff valves, and fire extinguishers are located. If a fire starts in a spray booth, immediately shut off the spray system and exhaust fans.
- Shut off electrostatic power and ground the charging system before adjusting, cleaning, or repairing electrostatic equipment.
- Clean, maintain, test, and repair equipment according to the instructions in your equipment documentation.
- Use only replacement parts that are designed for use with original equipment. Contact your Nordson representative for parts information and advice.

**Halogenated Hydrocarbon Solvent Hazards**

Do not use halogenated hydrocarbon solvents in a pressurized system that contains aluminum components. Under pressure, these solvents can react with aluminum and explode, causing injury, death, or property damage. Halogenated hydrocarbon solvents contain one or more of the following elements:

<table>
<thead>
<tr>
<th>Element</th>
<th>Symbol</th>
<th>Prefix</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fluorine</td>
<td>F</td>
<td>&quot;Fluoro-&quot;</td>
</tr>
<tr>
<td>Chlorine</td>
<td>Cl</td>
<td>&quot;Chloro-&quot;</td>
</tr>
<tr>
<td>Bromine</td>
<td>Br</td>
<td>&quot;Bromo-&quot;</td>
</tr>
<tr>
<td>Iodine</td>
<td>I</td>
<td>&quot;Iodo-&quot;</td>
</tr>
</tbody>
</table>

Check your material MSDS or contact your material supplier for more information. If you must use halogenated hydrocarbon solvents, contact your Nordson representative for information about compatible Nordson components.

**Action in the Event of a Malfunction**

If a system or any equipment in a system malfunctions, shut off the system immediately and perform the following steps:

- Disconnect and lock out system electrical power. Close hydraulic and pneumatic shutoff valves and relieve pressures.
- Identify the reason for the malfunction and correct it before restarting the system.
- If necessary, contact your Nordson service technician for assistance.

**Disposal**

Dispose of equipment and materials used in operation and servicing according to local codes.
# Description

See Figure 1. The PCI controller uses signals from a robot or cell controller to control the material dispensing rate. A constant bead size can be maintained by adjusting the material dispensing rate for changes in robot speed.

The PCI controller also
- displays recovery procedures if faults are detected.
- communicates faults to the robot controller.
- stores SPC and fault data.
- Controls material temperature of 4 independent zones (integrated TC model only).

# Specifications

Input Power: TYP 500 V, 3 Ø, 60 Hz, 10 A

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Alarm Tower-Alerts the operator that a fault condition exists within the system.</td>
</tr>
<tr>
<td>2</td>
<td>Touch Screen-Operator interface for the system. Refer to the Operator Interface section for more data.</td>
</tr>
</tbody>
</table>
| 3    | Operator Controls:  
START-Enables auxiliary power to the controller.  
POWER ON-Main power pilot light.  
STOP-Disables auxiliary power to the controller.  
FAULT RESET-Resets the servo drive if a fault occurs. |
Theory of Operation

The robot or cell controller sends a 0 to 10 volt DC analog signal that is proportional to the speed of the robot. This voltage can be a 12-bit word in the case of DeviceNet I/O systems, or a single-ended voltage in a discrete I/O system. The voltage controls the speed of the servomotor, which in turn controls the material flow rate, allowing the dispensed bead to remain constant through corners.

The material dispensing rates can be changed by using the Bead Size feature. The Bead Size feature controls the percentage of the robot analog signal to the servomotor. It also eliminates the need to change the robot program due to changes in the material dispensing rates. Increasing the bead size value increases the rate dispensing material. Decreasing the bead size value decreases the rate of dispensing material.

NOTE: A different bead size can be entered for each Part ID. A Global bead size can be entered if the bead size applies to all Part IDs.

Installation

! WARNING!

- Allow only qualified personnel to perform the following tasks. Follow the safety instructions in this document and all other related documentation.
- The robot controller contains electrical potentials that can be fatal. Disconnect and lock out electrical power before making connections.
- Read and understand this entire section before performing repairs. Contact a Nordson representative regarding these procedures if necessary.

1. Unpack the PCI controller and inspect it for dents, scratches, corrosion, or other physical damage. If there is any visible damage, call a local Nordson Corporation representative immediately.
2. Install the controller as close to the robot controller as possible.

Guidelines

Review the following guidelines:

- Hard-wire the controller to a dedicated power supply to provide safe operation and reduce interference from electrical noise.
- Install all electrical connections to local code.
- Install a locking disconnect switch or breaker in the service line ahead of any electrical equipment.
- Electrical, fluid, and air connections are dependent upon application requirements. Use the System Layout and Interconnect drawings provided with the system documentation for all connections.
- Make sure that there is enough slack in all hose and cable routings to allow for proper system operation.

NOTE: Most of the critical setup parameters that are described in this section are configured prior to shipment. The information on enabling/disabling pump and temperature control is provided for reference and should not be needed during a typical installation.

Schematics and Wiring Diagrams

See the system documentation for the schematics and wiring diagrams that are specific to your system.

<table>
<thead>
<tr>
<th>Controller</th>
<th>Schematic</th>
</tr>
</thead>
<tbody>
<tr>
<td>1083601 Controller, PCI, Dual Pro-Meter 500 V</td>
<td>1083602</td>
</tr>
</tbody>
</table>
Load Material into the System

Enable the Pump Stand

The pump stand must be enabled before the PCI controller can operate it. Perform the following to enable the pump stand:

1. Touch SYSTEM SETUP.
2. Touch the Nordson oval to access the hidden service menu.
3. Enter password 1111 in the password field.
4. Touch FAULT SETUP.
5. Set the PUMP STAND option to ENABLED. Touch SUBMIT to save changes. The pump stand appears on the Main Status screen.

6. Touch PUMP STAND to configure the pump faults and the timeout values for automatic depressurization. This feature allows the system to automatically depressurize at a preset time after the last dispense cycle.
Enable Temperature Control

The temperature control must be enabled before the PCI controller can operate it. Perform the following to enable the temperature control:

1. Touch **SYSTEM SETUP**.
2. Touch the Nordson oval to access the hidden service menu.
3. Enter password 1111 in the password field.
4. Touch **FAULT SETUP**.
5. Set the **TEMPERATURE** option to **ENABLED**. Touch **SUBMIT** to save the changes.
Temperature Control Setup

Use the Temperature Control Setup screen to adjust the temperature control loop gains and out of range limits for each control zone. A delay parameter can be set to turn off the temperature control after the pump stand depressurizes. To prevent material curing, this feature automatically stops the system from heating the hose and the meter.

Perform the following:
1. From the FAULT SETUP screen, touch TEMPERATURE. The Temperature Control Setup Screen appears.
2. Adjust the desired parameters using the keypad. Touch SUBMIT to save the changes.

Turn on the Temperature Control Contactor
1. From the main screen, touch either the temperature conditioning unit icon or SYSTEM SET-UP.
2. Touch TEMPERATURE STATUS.
3. Touch TEMP COND ON to turn on the heating zones. Touch TEMP COND OFF to turn off the heating zones.

Set the Temperature Setpoints
1. From the SYSTEM SETUP screen, touch TEMPERATURE SETPOINTS.
2. Select the desired parameter.
3. Use the keypad to change the value. Touch SUBMIT to save the changes.
**Fill the Material Circuit**

**WARNING**
Make sure that all material hose connections are tight before pressurizing the system.

1. Load a material drum into the bulk unloader(s).
   - **NOTE:**
     - Operation of this system only requires enough material pressure to move the piston back during meter refilling.
     - Use low air motor pressure to avoid rapid stroking as air is bled through the system.

2. Adjust the pump air motor pressure to 20-30 psi.

3. Pressurize the pump stand by touching either the changeover stand icon between the two unloaders or SYSTEM SETUP.

4. Touch PUMP STAND to access the pump control screen.

5. Touch PRESSURIZE.

6. Touch SYSTEM SETUP.

7. Touch the Nordson oval to access the hidden service menu.

8. Enter password 1111 in the password field.

9. Touch SDS MAINTENANCE.

10. Touch MANUAL to enable control of the dispense system from this screen.

11. Place a container below the dispense gun to catch material.

12. Touch the links in the VALVE CONTROL box to open the dispense gun and refill the solenoid valves.
   - **NOTE:**
     Close the refill valve first to prevent trapping pressure in the meter.

13. When a steady stream of material starts to flow from dispense gun, close the valves by touching the links.
   - **NOTE:**
     The system automatically closes both valves when the Auto Mode button is touched.
Configure the Robot Communication

The following paragraphs provide procedures for configuring the robot communication.

DeviceNet Configuration

1. Touch SYSTEM SETUP.
2. Touch the Nordson oval to access the hidden service menu.
3. Enter password 1111 in the password field.
4. Touch DEVICENET NODE. The DeviceNet Node Set-up screen appears.
5. Use the keypad to enter the DeviceNet node address and baud rate. Make sure to set the address and baud rate for both units of a dual controller.
6. Touch SUBMIT to save the changes.
7. Cycle power to the controller for the changes to take effect.
Configure the Robot Controller

Use the following information to configure the flow rate analog signal from the robot or cell controller.

Flow Rate Analog Setup:
Speed Proportional

See Figure 2. Configure the robot controller to vary the analog (commonly referred to as “tool speed”) signal from 0 to 10 Vdc over the full range of robot speed.

1. Determine the highest and lowest robot speeds to be used in production.
2. Configure the robot controller to output an analog #1 signal of +10 Vdc when the robot is moving at, or slightly above maximum speed.
3. Configure the robot controller to output the analog #1 signal of 0 Vdc when the robot is stationary.

NOTE:
Figure 2 represents an example of the approximate relationship between robot speed and analog #1 voltage as a guide for the operator. A robot speed of 80% corresponds to 8 Vdc. A robot speed of 40% corresponds to 4 Vdc.

Flow Rate Analog Setup:
Fixed or Point-to-Point

If the path to be programmed does not have complex motion, sharp corners, or variations in speed, the analog signal that controls flow rate can be set to a fixed value, simplifying robot programming.

![Figure 2 Relationship Between Analog Signal and Robot Speed](image-url)
**Set I/O Sequencing**

Refer to Table 3 and see Figure 4 for a description of the required signal sequence.

<table>
<thead>
<tr>
<th>Function</th>
<th>Sequence</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pre-Dispense</td>
<td>1</td>
<td>Check that the Nordson controller Dispenser Ready signal is ON.</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>Turn ON desired Part ID bit.</td>
</tr>
<tr>
<td></td>
<td>3</td>
<td>Wait 50 mS.</td>
</tr>
<tr>
<td></td>
<td>4</td>
<td>Turn ON Part Strobe signal. This is bit 10; same as old Style Strobe.</td>
</tr>
<tr>
<td></td>
<td>5</td>
<td>Wait for Nordson controller Dispenser in Process signal to turn ON. Dispenser in Process is the logical AND of the old Dispenser in Process and Meter Prepressurized. It indicates system is in the dispense cycle AND prepressurized.</td>
</tr>
<tr>
<td></td>
<td>6</td>
<td>Wait 50 mS after receiving Dispenser in Process signal.</td>
</tr>
<tr>
<td>Dispense</td>
<td>7</td>
<td>Set robot analog output to desired dispense rate. Dispense rate can be set earlier if desired.</td>
</tr>
<tr>
<td></td>
<td>8</td>
<td>Set and reset Gun On signal as required for the path.</td>
</tr>
<tr>
<td>Ending Part Cycle</td>
<td>9</td>
<td>Wait at least 50 mS after part segment's last Gun On signal is turned OFF.</td>
</tr>
<tr>
<td></td>
<td>10</td>
<td>Pulse Dispense Complete ON for at least 50 mS duration.</td>
</tr>
<tr>
<td></td>
<td>11</td>
<td>Nordson controller turns Dispenser in Process signal OFF.</td>
</tr>
<tr>
<td></td>
<td>12</td>
<td>Wait at least 250 mS before checking for Nordson controller Volume OK signal.</td>
</tr>
<tr>
<td></td>
<td>13</td>
<td>Turn OFF Part Strobe signal.</td>
</tr>
<tr>
<td></td>
<td>14</td>
<td>Nordson controller turns Volume OK signal OFF.</td>
</tr>
<tr>
<td></td>
<td>15</td>
<td>Wait for Nordson controller Dispenser Ready signal to be ON; indicates refill complete.</td>
</tr>
<tr>
<td></td>
<td>16</td>
<td>Ready to dispense next part/bead.</td>
</tr>
</tbody>
</table>

**Figure 4   Signal Sequence**
\section*{I/O Signal Descriptions}

Refer to the following tables for the IO signal descriptions.

\subsection*{Input Signals}

<table>
<thead>
<tr>
<th>Signal</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Part ID bits 1-8</td>
<td>These 8 bits define the Part Style to be dispensed. Up to 256 individual parts can be defined in terms of bead size, target volume setpoint, and prepressure setpoint. If none of the bits are HIGH at the rise of the strobe input, part ID ZERO is used. The bits may be dropped any time after the strobe is raised without affecting the value active during that part cycle.</td>
</tr>
<tr>
<td>Part Strobe</td>
<td>This input is Dispense Enable signal. When it is LOW, the dispense controller ignores all other inputs, resulting in no dispensing. If this input is dropped during the dispensing cycle, the part will be aborted. Any volume that has been dispensed is cleared from the volume total and faults regarding volume target error will not be posted. The meter refills when this signal is dropped to abort a part. The rise of this input causes the meter to pressurize in preparation for the dispense cycle.</td>
</tr>
<tr>
<td>Gun On</td>
<td>When this input is HIGH, the outlet valve opens and the meter moves forward to dispense material at a rate determined by the analog voltage from the robot and the bead size setting used.</td>
</tr>
<tr>
<td>Dispense Complete</td>
<td>This input is a pulse at least 50 mS in duration that must be sent after the last gun on input for the part cycle is dropped. It causes the volume total to be calculated and to be compared against the target volume setpoint. This input refills the meter if the meter is set to Refill After Every Part. If the meter is set to Refill After Setpoint Is Reached, this input causes the part’s volume to be added to a running total, and will not cause a refill until the total has exceeded the value entered for Refill Setpoint.</td>
</tr>
<tr>
<td>Fault Reset</td>
<td>The rising edge of this pulse input resets any faults that are not Self-Clearing.</td>
</tr>
<tr>
<td>Remote Start</td>
<td>This input should be a pulse of at least 500 mS in duration. It causes the material supply pump to pressurize and energizes the contactor of the heater circuits. This allows the system to be prepared for production without having an operator go to the controller.</td>
</tr>
<tr>
<td>Purge</td>
<td>This input causes the meter to be purged at a rate set in the Service Menu screen named Meter Setup. The meter purges when this input is held HIGH, or until the Extend Prox switch is reached. When the input is dropped the meter will refill.</td>
</tr>
</tbody>
</table>
## Output Signals

<table>
<thead>
<tr>
<th>Signal</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dispenser Ready</td>
<td>This output indicates that the PCI controller is ready to dispense and that no faults are present that will affect the performance of the system. Individual faults that are set to Major can cause this output to be held LOW. Program the robot to check for this output to be HIGH before attempting to run a part cycle.</td>
</tr>
<tr>
<td>Dispense In Process</td>
<td>This output goes HIGH when the controller receives a Part Strobe input and when the servomotor moves far enough forward to pressurize the meter to the value programmed in Service Menu on the Prepressure Setpoints screen. This pressure setpoint can be set to different values for each Part ID and is helpful in assuring that the start of the material bead is correct. Program the robot to wait for this output to go HIGH before the first Gun On input is raised.</td>
</tr>
<tr>
<td>Auto Mode</td>
<td>This output is HIGH until the operator places the controller in the Manual mode. The robot can use this output as a confirmation that dispensing can be performed. When the controller is in the Manual mode, Dispenser Ready is forced to LOW.</td>
</tr>
<tr>
<td>Volume OK</td>
<td>This output is raised at the end of a part cycle if the volume dispensed is within the MAJOR HIGH/LOW percentages of the Target Volume set on the Meter Faults menu. Use this output to determine if a part is acceptable for processing or if it should be rejected.</td>
</tr>
<tr>
<td>Major Fault</td>
<td>This output is raised when a fault defined as a major fault has been detected. Major faults will cause Dispenser Ready to be forced LOW.</td>
</tr>
<tr>
<td>Minor Fault</td>
<td>This output is raised when a fault defined as a minor fault has been detected. Minor faults do not affect the Dispenser Ready output.</td>
</tr>
<tr>
<td>Remote Start In Progress</td>
<td>This output goes HIGH when the controller receives a Remote Start input pulse. The output remains HIGH until all the conditions are met to restore Dispenser Ready such as the pump stand pressurized and the temperature zones within their defined setpoint limits.</td>
</tr>
</tbody>
</table>
**Meter Setup**

Perform the following to setup the meter to be used with the PCI controller.

1. Touch SYSTEM SETUP.
2. Touch the Nordson oval to access the hidden service menu.
3. Enter password 1111 in the password field.
4. Touch METER SETUP. The Meter Fault Setup screen appears.

**Refill After Setpoint Reached**

To allow more efficient use of the meter when dispensing small volumes, the controller can be set to only refill after a setpoint is reached.

1. Touch the drop down box in the Refill after field.
2. Set the box to After setpoint is reached.
3. Touch SUBMIT to save changes.

The meter will only be refilled after the value entered in the Refill Setpoint field is accumulated.

**Piston Size**

This value must be set to match the meter being controlled to ensure accurate volume reporting.

**Fine Tune Meter Counts**

This field allows the encoder input to be precisely adjusted in volume-critical applications. Use an accurate scale to weigh dispensed shots of material and compare the dispensed volume using specific gravity with the reported volume.

**Purge Speed**

This value should be reduced as necessary to prevent overpressurizing the meter during manual or robot purges when high-viscosity materials are dispensed.

**Transducer Ranges**

These fields must be set to match the range of the transducer used to ensure accurate pressure reporting.

**NOTE:**

The SDS systems do not typically use an upstream transducer.
**Meter Fault Setup**

Perform the following to setup the meter that is being used with the PCI controller.

1. Touch **SYSTEM SETUP**.
2. Touch the Nordson oval to access the hidden service menu.
3. Enter password 1111 in the password field.
4. Touch **METER FAULTS**. The Meter Fault Setup screen appears.

**Major / Minor High Alarms**

The values entered in these fields define the percentage of target volume that can be dispensed above the target value before a major fault (dispenser ready forced low) or a minor fault (dispenser ready not affected) occurs.

**Major / Minor Low Alarms**

The values entered in these fields define the percentage of the target volume that can be dispensed below the target value before a major fault (dispenser ready forced low) or a minor fault (dispenser ready not affected) occurs.

**Refill Timeout**

This value sets the time for the meter to be refilled after a part cycle before a major fault is set. This fault automatically resets when the piston target disk reaches the refill proximity switch.

**Pre-Pressure Timeout**

This value sets the time for the meter to reach the pre-pressure setpoint at the start of the part cycle before a major fault is set.

**Meter Overpressure Limit**

This value sets the pressure limit to stop the servomotor and post a major fault.
**Pre-Pressurization Setpoints**

Perform the following to optimize the start of the dispensed bead.

1. Touch **SYSTEM SETUP**.
2. Touch the Nordson oval to access the hidden service menu.
3. Enter password 1111 in the password field.
4. Touch **Prepressure Setpoints**. The Meter Fault Setup screen appears.

The value entered for prepressure should be close to the dynamic value seen during dispensing of the specific part ID.

When the style strobe is received, the ball screw will begin moving forward until the prepressure value entered for the current Part ID is reached. At this point, the ball screw stops and the Meter Prepressurized signal is sent to the robot, indicating that dispensing can begin.
Target Volume Setpoints / Alarms

For each part ID, a target volume value must be entered equal to the desired volume of the part.

Enter target volumes as integer values; no decimal point. For example, to enter a target volume of 31.5 CC, enter 315 and touch SUBMIT to save the changes.

Alarm values should also be entered that define the acceptable percentage above and below the target before a fault is posted. Both these menus are accessed via the hidden service menu.
Operator Interface and Screens

This section describes the SDS screens.

Touch the screen to select one of seven main menus (1):

- SYSTEM STATUS
- VIEW FAULTS
- TEST POINTS
- SYSTEM SET-UP
- PROCESS DATA
- ONLINE MANUAL
- PREV. MAINT. (Preventive Maintenance)

Refer to Table 4 for a description of the operator interface functions.

SYSTEM STATUS

The SYSTEM STATUS screen (5) is the default screen displayed at power up.

This screen shows the layout of major system components including material supply pumps, the SDS Meter, and the controller itself. Each component image can flash red when a fault condition occurs involving that component. When an image is flashing, touching the flashing image or VIEW FAULTS takes the user to the VIEW FAULTS screen where detailed information on the fault and recovery instructions is appears.

The status screen also features indicators for the status of digital inputs (9) and meter pressure (6).
<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>MENU BUTTONS</td>
<td>Access to various screens and setup menus.</td>
</tr>
<tr>
<td>2</td>
<td>DISPENSER STATUS</td>
<td>Green when Ready, Red if Not Ready.</td>
</tr>
<tr>
<td>3</td>
<td>FAULT INDICATOR FIELD</td>
<td>Displays latest current fault message.</td>
</tr>
<tr>
<td>4</td>
<td>ITALIAN FLAG</td>
<td>Touch to display Italian language.</td>
</tr>
<tr>
<td>5</td>
<td>USA FLAG</td>
<td>Touch to display English language.</td>
</tr>
<tr>
<td>6</td>
<td>CURRENT PART VOLUME</td>
<td>Visually indicates the percent of the job that is completed and the actual dispense volume at the end of the part cycle.</td>
</tr>
<tr>
<td>7</td>
<td>NEXT CONTROLLER</td>
<td>Use to toggle between systems.</td>
</tr>
<tr>
<td>8</td>
<td>UNIT NAME</td>
<td>User-defined label; indicates the current operator interface that is displayed on the screen. The user-defined label can be up to 10 characters.</td>
</tr>
<tr>
<td>9</td>
<td>SYSTEM STATUS</td>
<td>Appears as the default screen; displays the system configuration.</td>
</tr>
<tr>
<td>10</td>
<td>TEMPERATURE</td>
<td>Displays meter and hose temperatures.</td>
</tr>
<tr>
<td>11</td>
<td>PRESSURE</td>
<td>Displays system operating pressure.</td>
</tr>
<tr>
<td>12</td>
<td>BEAD SIZE</td>
<td>Bead size is percentage of robot analog sent to motor. Touch to access adjustment menu.</td>
</tr>
<tr>
<td>13</td>
<td>PART I.D.</td>
<td>Displays the current part I.D.</td>
</tr>
<tr>
<td>14</td>
<td>I/O INDICATORS</td>
<td>Displays status of primary robot dispense signals.</td>
</tr>
</tbody>
</table>
VIEW FAULTS

The VIEW FAULTS screen displays the description of the current fault(s) and the corrective action required.

Touch VIEW HELP/FAULT LOG to toggle between the fault log and help screens.

Touch FAULT LOG to view the history of faults by time and date (most recent at top).

Touch RESET FAULTS at the top of screen or CLEAR ALL FAULTS at the bottom of the screen to clear the current faults. Note that this only applies to non-self-clearing faults.
TEST POINTS

These screens are used to verify the state of IO signals to/from the robot and peripheral devices (pump stand, temp controller, etc.).

NOTE:

The refresh rate of the browser can affect the ability of the indicators to light in response to fast-acting signals. Touch NEXT I/O SCREEN to toggle through the available IO screens.
SYSTEM SET-UP

Use the SYSTEM SET-UP screen to configure the system parameters and to access control screens for pumps and temperature controller. The following paragraphs provide a description of each link.

Clock

The time and date used in the Process Data screen, and in the stored SPC and fault logs is based on a clock that runs on the PCI controller board. To synchronize the onboard clock with the time set in the PC, touch the link named Update controller with current time.

To view the current PC time/date, touch Clock Options link. The Clock Set-up screen appears.

NOTE:
The time and date fields are read-only, changes to the PC clock should be done by minimizing the browser window and opening the Windows clock.

To select the SPC time format, use the drop down box to select either 12 Hour Format or 24 Hour Format.
System

Touch the keyboard to select
- System unit type (Metric or US)
- Clock format (24 Hrs or 12 Hrs)
- Pressure unit type (Metric or US)
- Bead Size Option (Global or Part ID)
- Temperature Units (°F or °C)

Pump Stand Control

Touch Pump Stand on the System Setup menu or touch the crossover valve stand between the pump icons of the System Status screen to open the Pump Stand Control screen.

Touch the PRESSURIZE button to pressurize the pump stand.

Touch the DEPRESSURIZE button to depressurize the pump stand.

NOTE:
The length of time the depressurization valve remains open is user-adjustable through the hidden service menu. The length of time required to depressurize the system can vary depending on material viscosity and system volume.

Temperature Setpoint

The Temperature Setpoint screen displays the current and setpoint temperatures for each temperature control unit (TCU) zone. Use the keypad to change a TCU zone temperature.
Temperature Conditioner Status
and Manual ON/OFF

The Temperature Status screen displays each TCU zone temperature. Touching TEMP COND ON enables the TCU. Touching TEMP COND OFF disables the TCU.

Manual Operation

Use this screen to manually operate the meter. The system must be placed in MANUAL mode before the various buttons will function.

NOTE:
Depending on the application software, it may be necessary to raise the input Over Purge Bucket to execute manual and automatic purging.

To purge the meter, place the controller in MANUAL MODE and touch PURGE ON. The meter will start to dispense at a settable rate until PURGE OFF button is touched or until the meter dispenses its entire volume.

If desired, touch FWD or REV to jog the motor at 5 percent speed.

NOTE:
The dispense gun will open whenever FWD is touched to avoid overpressurizing the system.

Touching either REFILL or AUTO MODE causes the meter to refill. Touching HOME causes the ballscrew to move to its park position without refilling the cylinder.
Restore Configuration

Use the drop-down list box on the Restore Configuration screen to reload either of two previously-stored configurations from battery-backed RAM. This is useful to return to a known good set of parameters when adjusting dispense settings.

Simulation Mode

The Simulation Mode screen is used to dispense part cycles without the use of the robot. The dispensed parts are logged on the Process Data screen.

PROCESS DATA

Touch PROCESS DATA to view production data. This list will show the last 11 part cycles in first-in and first-out order.
ONLINE MANUALS

Touch ONLINE MANUALS for links to documentation for major system components.

PREV. MAINT.

Touch PREV. MAINT. to view preventive maintenance data.
**Bead Size**

Touch **Bead Size** to view and adjust bead sizes. Bead size is an arbitrary number between 1 and 99. Bead sizes can be either by Part ID or Global.

A Part ID bead size value applies to one part. Up to 256 Part ID bead sizes can be entered.

A Global bead size value applies to all Part IDs. If the Global bead size value changes, the bead size for all Part IDs change to that value.

Touch the applicable link on the **Bead Size Menu** to access the **Bead Size Setup** screen and change the bead sizes.
Operation

**WARNING**

- Allow only qualified personnel to perform the following tasks. Follow the safety instructions in this document and all other related documentation.
- Read and understand this section before operating the PCI controller. The procedures in this section assume that the PCI controller was configured by a Nordson Corporation representative.

**NOTE:**

- Before operating the controller, make sure that each robot is taught the proper tool path. Refer to the robot controller manual for procedures.
- When entering data, touching the field next to the corresponding parameter positions the cursor inside of the field.

Some parameters require the use of the screen keyboard to enter data. When entering data, touch:

- **CLEAR** to delete the current value in a field.
- **BACK SP** to backspace.
- **RESET** to restore a value.
- **SUBMIT** to save changes.

**NOTE:**

The system software only recognizes integer values. Do not use the decimal point button when entering numerical values.
Startup

NOTE:
Operating procedures may vary due to specific application requirements. Refer to your System Parameter Sheet for specific operating settings.

1. Turn on power to the controller. After the system finishes the boot-up process, press the POWER ON button.
2. Place a waste container under the dispense gun.
3. Start the temperature controller zones as required and pressurize the bulk unloader. When temperatures reach their setpoints, any temperature zone faults will Self-Clear.
4. To purge the nozzle manually, perform the following steps:
   b. Touch Manual to place the controller in the manual mode.
   c. Touch PURGE ON to begin dispensing. The meter will continue to purge until empty or PURGE OFF is touched.
   d. Touch PURGE OFF to stop dispensing.
   e. Touch REFILL to refill the meter, or touch Auto Mode to put the system back into AUTO mode, at which time a refill will automatically be performed.
5. Check the bead size for the part being run. Touch BEAD SIZE to access the Bead Size Menu and make adjustments if necessary.
6. Touch PROCESS DATA to monitor material dispensing characteristics.
7. Position the part and begin dispensing from the robot controller.

NOTE:
During dispensing, the robot signal indicators illuminate when signals are received from the robot controller. During normal operation, these lights flash on and off in specific sequence. Due to the screen refresh rate of the browser, fast-changing signals may not always light the indicators.

Bead Size Adjustment

Touch BEAD SIZE at the bottom of the status screen to access the bead size adjustment screen. Bead size is an arbitrary number between 1 and 99, and can be thought of as the percentage of robot analog voltage sent to the servomotor during dispensing.

Bead size values can be entered either by Part ID (specific part) or Global (applies to all parts).

Fault Messages

If a fault is detected during operation, the alarm tower red light turns on and the type of fault is indicated on the operator interface.

Touch VIEW FAULTS. A description of the current fault appears along with the corrective action. Note that some faults are self-resetting, meaning that the fault condition must be corrected before the fault will automatically clear. Pressing the fault reset button does not reset self-resetting faults.
Restoring Configuration Settings

Use the drop-down list box to reload either of two previously-stored configurations from battery-backed RAM. This is useful to return to a known good set of parameters when adjusting dispense settings.


**Shutdown**

Use the following shutdown procedure to remove power from the PCI Controller:

1. Touch **Minimize** (1) at the top of a screen display.
2. Touch **start** (2) on the Windows task bar to access the **Start Menu**.
3. Touch **Shut Down** (3) on the **Start Menu**.
4. Make sure that **Shut Down** is displayed in the **Shut Down Windows** field. Touch **OK** (4).
5. Turn the controller off and relieve all pressures.

**Shutdown Screens**
Statistical Process Control Data and Fault Logs

The statistical process control (SPC) data that appears on the Process Data screen is stored on the hard drive of the controller PC. Stored values include:

- Date and Time
- Part ID
- Bead Size Setting
- Volume dispensed

Accessing SPC Data using Log File Manager Utility

The PCI controller saves part and fault data in comma-delimited format for importing into a spreadsheet. Use the following procedure to export the log files onto a USB memory device:

1. Insert a USB memory stick into the port on side of the cabinet.
2. In the hidden service menu, select Log File Manager.
3. Select Run this program from current location option. Click OK.
4. Click on the Yes button.
5. Select the desired file to be exported by touching the file name in the list box.
6. Select the destination drive and folder, then press Export Selected Log File(s) button.
7. Exit the program.

SPC Error and System Status Codes

The PCI controller collects the following SPC Error Codes and SPC System Status Codes. Refer to Tables 5 and 6 for the Error and System Status codes.

Table 5 SPC Error Codes

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>High dispensed volume</td>
</tr>
<tr>
<td>2</td>
<td>Low dispensed volume</td>
</tr>
<tr>
<td>4096</td>
<td>Robot signals out of sequence</td>
</tr>
<tr>
<td>8192</td>
<td>Gun or controller failure</td>
</tr>
<tr>
<td>16384</td>
<td>Auxiliary device failure either temperature conditioning unit or pumps</td>
</tr>
</tbody>
</table>

Table 6 SPC System Status Codes

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>128</td>
<td>New configuration file or defaults have been loaded</td>
</tr>
<tr>
<td>256</td>
<td>SPC data has been downloaded</td>
</tr>
<tr>
<td>512</td>
<td>Dispenser Ready went from low to high prior to dispense cycle</td>
</tr>
<tr>
<td>1024</td>
<td>Dispenser Ready was low but robot attempted to run a part</td>
</tr>
<tr>
<td>32768</td>
<td>Part cycle ran in Simulation Mode</td>
</tr>
</tbody>
</table>
# Troubleshooting

This section contains troubleshooting procedures. These procedures cover only the most common problems that you may encounter. If you cannot solve the problem with the information given here, contact your local Nordson representative for help.

> **WARNING**
> Allow only qualified personnel to perform the following tasks. Follow the safety instructions in this document and all other related documentation.

<table>
<thead>
<tr>
<th>Problem</th>
<th>Possible Cause</th>
<th>Corrective Action</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>1. Meter does not dispense</strong></td>
<td>Major fault</td>
<td>Access the VIEW FAULTS screen to determine cause of fault condition.</td>
</tr>
<tr>
<td></td>
<td>Controller in Manual Mode</td>
<td>Set PCI controller to the AUTO mode.</td>
</tr>
<tr>
<td></td>
<td>No air to meter solenoids</td>
<td>Check supply air to the gun and refill meter solenoids. Make sure that the regulator is set to at least 70 psi.</td>
</tr>
<tr>
<td></td>
<td>Robot signals not in proper sequence</td>
<td>See the IO timing chart (Figure 4) for proper robot IO sequence.</td>
</tr>
<tr>
<td><strong>2. Meter does not refill</strong></td>
<td>Low unloader pressure</td>
<td>Confirm that pump has been pressurized. Check the air pressure to the bulk unloaders. Make sure that there is enough air pressure to refill the meter cylinders.</td>
</tr>
<tr>
<td></td>
<td>No air to meter solenoids</td>
<td>Check supply air to the gun and refill meter solenoids. Make sure that the regulator is set to at least 70 psi.</td>
</tr>
<tr>
<td></td>
<td>Clogged refill valve(s)</td>
<td>Remove the refill valve and either clean or replace the refill valve cartridge.</td>
</tr>
<tr>
<td></td>
<td>Refill proximity switch not within limits.</td>
<td>Make sure that the gap between the refill proximity switch and the piston target disk does not exceed 0.030 in. and that the alignment is correct. Adjust the proximity switch if necessary.</td>
</tr>
<tr>
<td><strong>3. Bead deposition &quot;wiggles&quot;</strong></td>
<td>Nozzle too high above work piece</td>
<td>Modify robot path to lower the nozzle.</td>
</tr>
<tr>
<td></td>
<td>Material speed through nozzle too low</td>
<td>Increase the bead size setting or robot analog voltage. Refer to Startup in the Operation section.</td>
</tr>
<tr>
<td></td>
<td>Nozzle not large enough</td>
<td>Install a larger nozzle. Contact your Nordson Corporation representative for part numbers.</td>
</tr>
<tr>
<td><strong>4. Unexpected bead-size change</strong></td>
<td>Nozzle partially blocked</td>
<td>Remove nozzle; clean or replace.</td>
</tr>
<tr>
<td></td>
<td>Material exceeded shelf life</td>
<td>Use fresh material.</td>
</tr>
</tbody>
</table>
Repair

Repairs consist of replacing the operator interface panel and the PCAs.

**WARNING**

- Allow only qualified personnel to perform the following tasks. Follow the safety instructions in this document and all other related documentation.
- Disconnect equipment from line voltage. Failure to observe this warning may result in personal injury, death, or equipment damage.

**Operator Interface Panel**

Perform following procedure to replace the operator interface.

**NOTE:**

Do not apply sealing compounds to the operator interface. The operator interface has a sealing gasket that forms a compression-type seal.

1. Turn off and lock out external electrical power to the controller.
2. See Figure 5. Open the enclosure door (1).
3. Disconnect the AC (4) and Serial (5) cables from the operator interface (3).
4. Remove the mounting clips (2) securing the operator interface to the enclosure door. Remove the operator interface from the enclosure door.
5. Make sure that the sealing gasket on the operator interface is properly positioned.
6. Install the new operator interface into the enclosure door (1).
7. Install the mounting clips (2). Using the torque sequence shown in Figure 5, tighten the mounting clips to 10 in.-lb (1.1 N·m). To prevent flexing the touchscreen, do not overtighten the clips.
8. Connect the AC (4) and Serial (5) cables to the operator interface, being careful to install the serial cable to the com port it was removed from.
9. Close the enclosure door (1).

**PCA Replacement**

**! WARNING !**

This unit contains electrostatic sensitive devices (ESD). Always wear a grounding wrist strap to prevent damage to ESD parts.

1. Turn off and lock out external electrical power to the controller.
2. See Figure 5. Open the enclosure door.
3. Disconnect the electrical connectors from the PCA.
4. Remove the mounting screws from the PCA.
5. Install the new PCA. Do not over tighten the screws.
6. Re-install the electrical connectors.
7. Close the enclosure door.

---

Figure 5 Operator Interface and PCA Replacement
Restoring PCI Controller Programs

! WARNING !
Allow only qualified personnel to perform the following tasks. Follow the safety instructions in this document and all other related documentation.

Use this procedure to restore the PCI controller program and parameter configuration.

1. Open the enclosure door.
2. Connect a mouse and keyboard to the VersaView PC.

NOTE:
If a standard PS-2 style keyboard is used, the VersaView PC will have to be rebooted to recognize the keyboard.

3. Reboot the VersaView PC if necessary.
4. Close all running programs.
5. Log out as the PCI user and log in as the Administrator. Enter the password. The default password is Nordson.
6. Using Windows Explorer, access the C:\PCI_Install\PCI_Loader folder.
7. Double-click on the PCI Loader.exe file to run the PCI Program Loader utility.
8. Cycle power to the PCI controller circuit board. Refer to the PCI controller schematic for details.
9. When power is restored to the board, the message in the PCI Controller State field changes from Not Ready to Controller Ready.
10. Click on Open File (9) and select the desired srec file. Click on Update PCI (8).
11. The time and file loading progress appears in the Elapsed Time (4) and the File Progress (5) fields.
12. When the process is done, the board will reboot indicated by flashing of the 1st output LED on the board. Click on EXIT (6) to exit Loader utility.
13. Disconnect the keyboard and mouse from the VersaView PC.
14. Close the enclosure door and cycle power to the PCI controller.
Saving and Loading PCI Controller Configurations

**WARNING**
- Allow only qualified personnel to perform the following tasks. Follow the safety instructions in this document and all other related documentation.
- Disconnect equipment from line voltage. Failure to observe this warning may result in personal injury, death, or equipment damage.

**NOTE:**
Loading a configuration file from a floppy disk does not require a keyboard. Proceed to the Loading Configurations procedure.

Connect a USB-type keyboard to the VersaView PC to enter a file name and save configuration data onto a floppy disk or the hard drive.

**NOTE:**
If a standard PS-2 style keyboard is used, the VersaView PC will have to be rebooted to recognize the keyboard.

---

**Saving Configurations**
1. Touch **Minimize** on the **System Status** screen to minimize the browser screen.
2. Maximize the **SerialCom** window.
3. Touch either Unit 1 or Unit 2 in the **Config File Transfer** field (3) to save data from the applicable controller board.
4. Touch **Save Config File** (4). Using the keyboard, enter the name of the file to save in the file-name field. Touch **Save** (2).
5. When **OK-File Saved** appears in the field (5), minimize the **SerialCom** window (1).
6. Touch **Maximize** on the **System Status** screen to maximize the browser screen.
7. Close the enclosure door.
Loading Configurations

1. Touch Minimize on the System Status screen to minimize the browser screen.
2. Maximize the SerialCom window (1).
3. Touch either Unit 1 or Unit 2 in the Config File Transfer field (3) to load data to the applicable controller board.
4. Touch Load Config File (4).
5. Select the desired file to load and touch Open.
6. Wait for the PCI controller to update. When Transfer Complete appears in the field (5), minimize the SerialCom window (1).
7. Touch Maximize on the System Status screen to maximize the browser screen.
8. Close the enclosure door.
Parts
See Figure 6 and the following parts lists. To order parts, call the Nordson Customer Service Center or your local Nordson representative.

<table>
<thead>
<tr>
<th>Item</th>
<th>Part</th>
<th>Description</th>
<th>Qty</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1040541</td>
<td>Touch screen assembly</td>
<td>1</td>
</tr>
<tr>
<td>2</td>
<td>1062216</td>
<td>Servo Drive, Ultra, 2kW</td>
<td>2</td>
</tr>
<tr>
<td>3</td>
<td>1040513</td>
<td>Relay, solid state</td>
<td>4</td>
</tr>
<tr>
<td>4</td>
<td>1040549</td>
<td>IO Module, 10-in 10-out</td>
<td>1</td>
</tr>
<tr>
<td>5</td>
<td>1050540</td>
<td>Module, I/O DeviceNet, RTD</td>
<td>1</td>
</tr>
<tr>
<td>6</td>
<td>1072509</td>
<td>PCA, PCI main board</td>
<td>1</td>
</tr>
<tr>
<td>7</td>
<td>- - - -</td>
<td>Servo drive</td>
<td>1</td>
</tr>
</tbody>
</table>

Figure 6  Controller Parts